

# Geometrical Sample Reweighting for Monte Carlo Integration

Jerry Guo & Elmar Eisemann  
TU Delft

# Monte Carlo Integration

The standard solution for offline rendering

$$\hat{I} = \frac{1}{N} \sum_{i=1}^N f(x_i)$$



# Monte Carlo Integration

The standard solution for offline rendering

$$E[\hat{I}] = \lim_{N \rightarrow \infty} \frac{1}{N} \sum_{i=1}^N f(x_i) = \int f(x) dx$$



# Monte Carlo Integration

The standard solution for offline rendering



> hours





# Monte Carlo Integration



# Monte Carlo Integration

## Variance reduction

Importance sampling

Quasi Monte Carlo



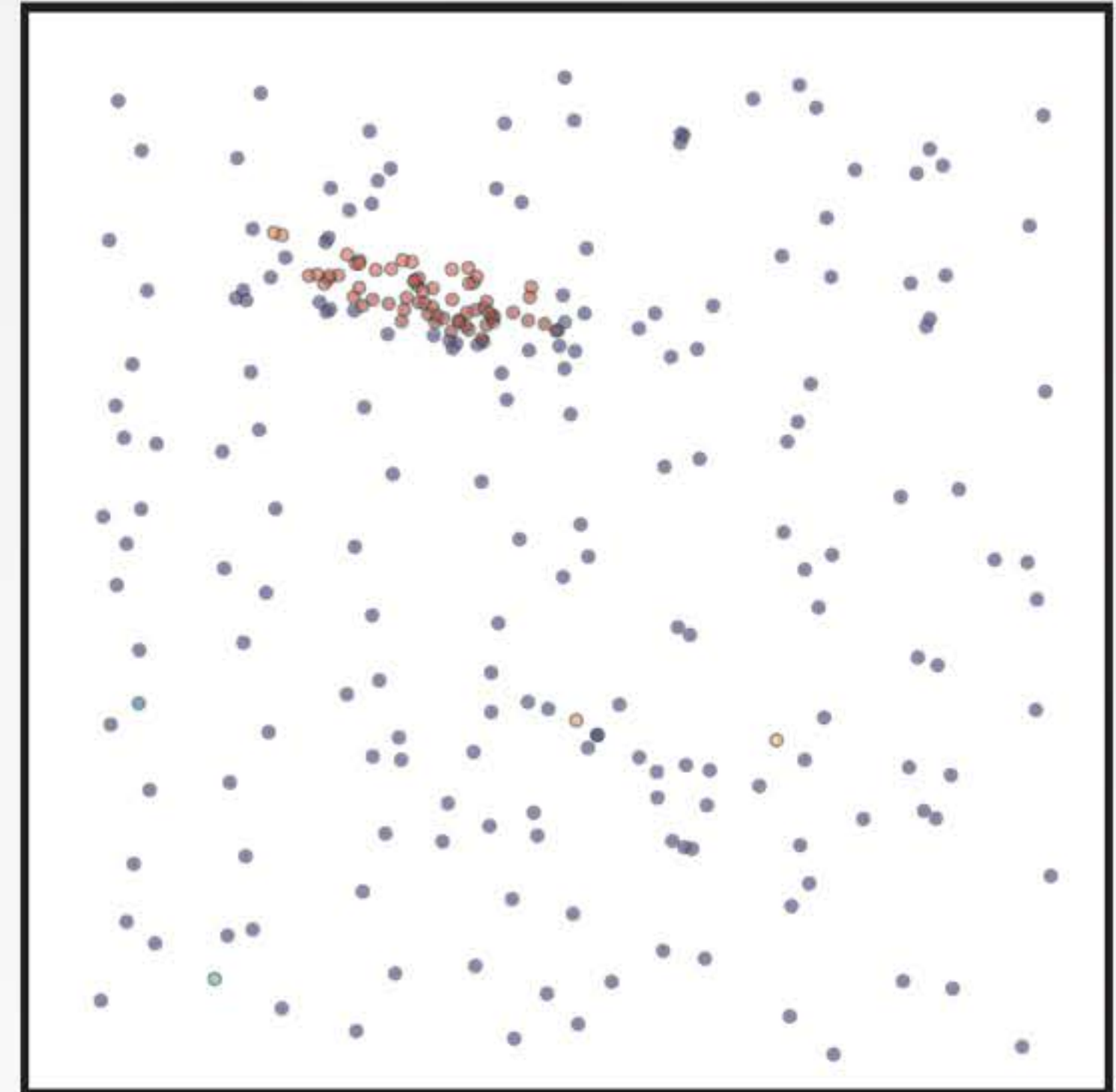


# Monte Carlo Integration

## Importance sampling

Non-uniform samples

Un-equal sample weights

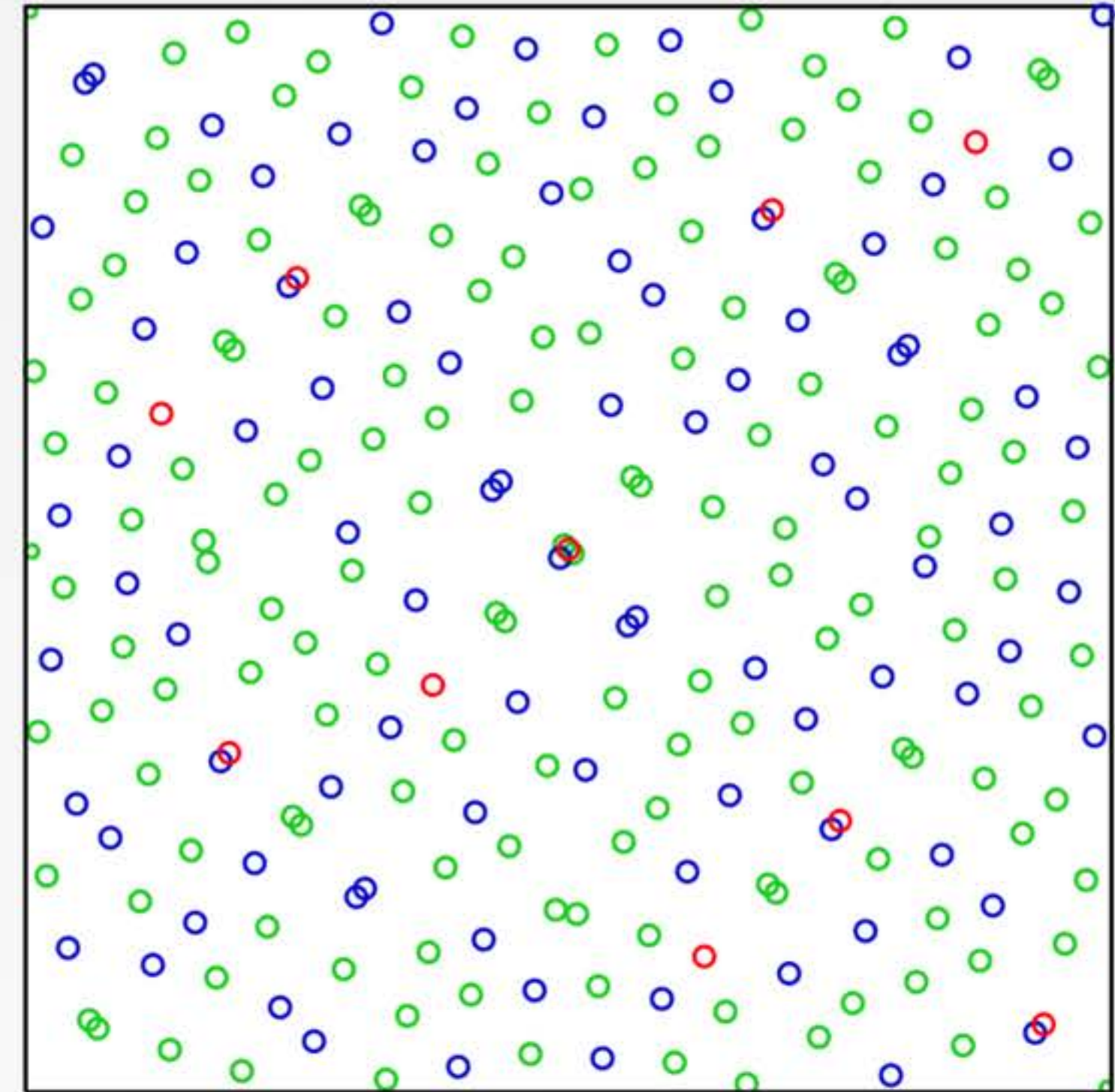


# Monte Carlo Integration

## Quasi Monte Carlo

Uniform deterministic samples

Equal sample weights





# Monte Carlo Integration

## Uniformity vs. Randomness

Distribution hard to craft

Correlated samples leads to alias



# Monte Carlo Integration

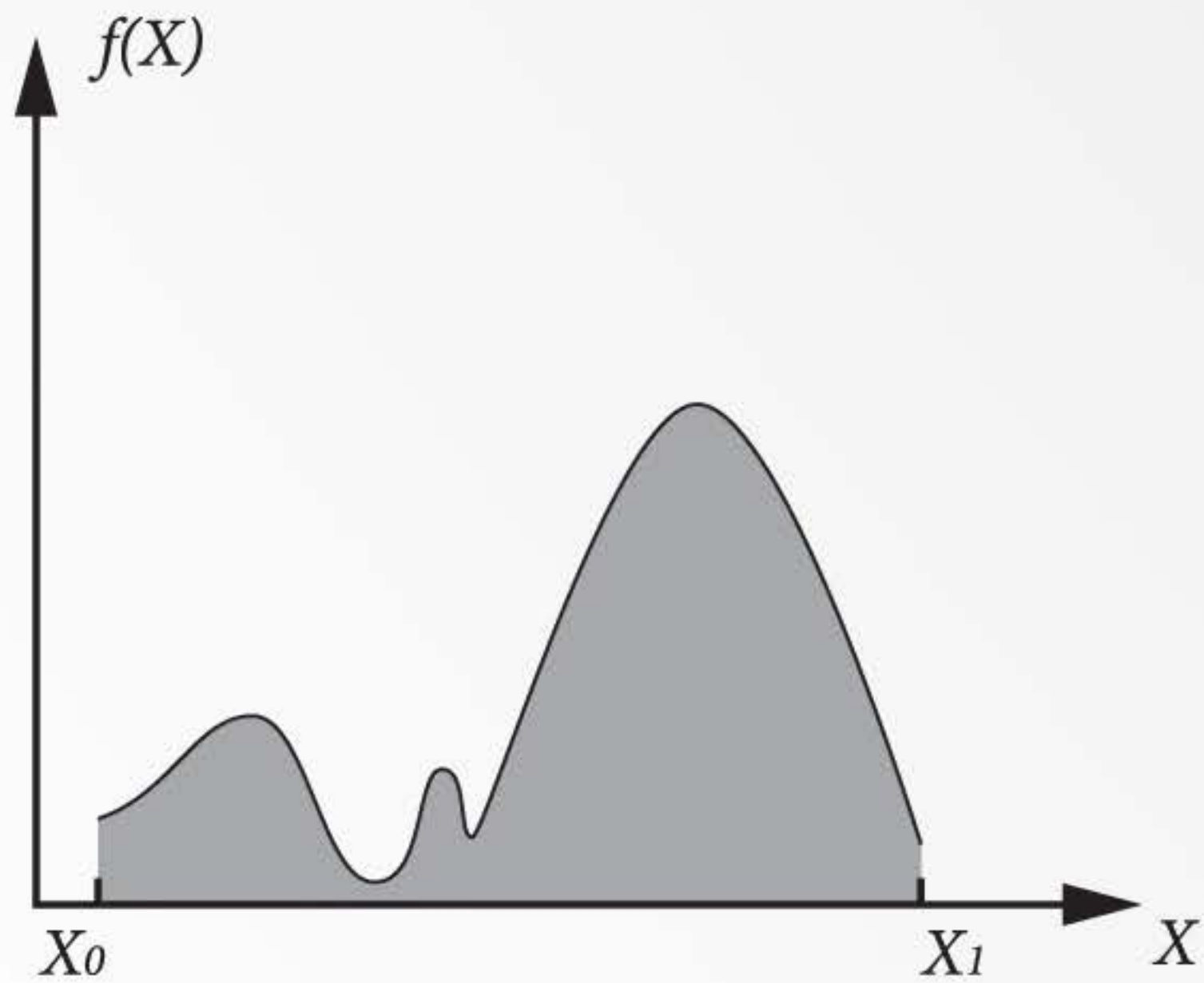
## Geometrical Sample Reweighting

Maintain randomness

Reweighted uniformity

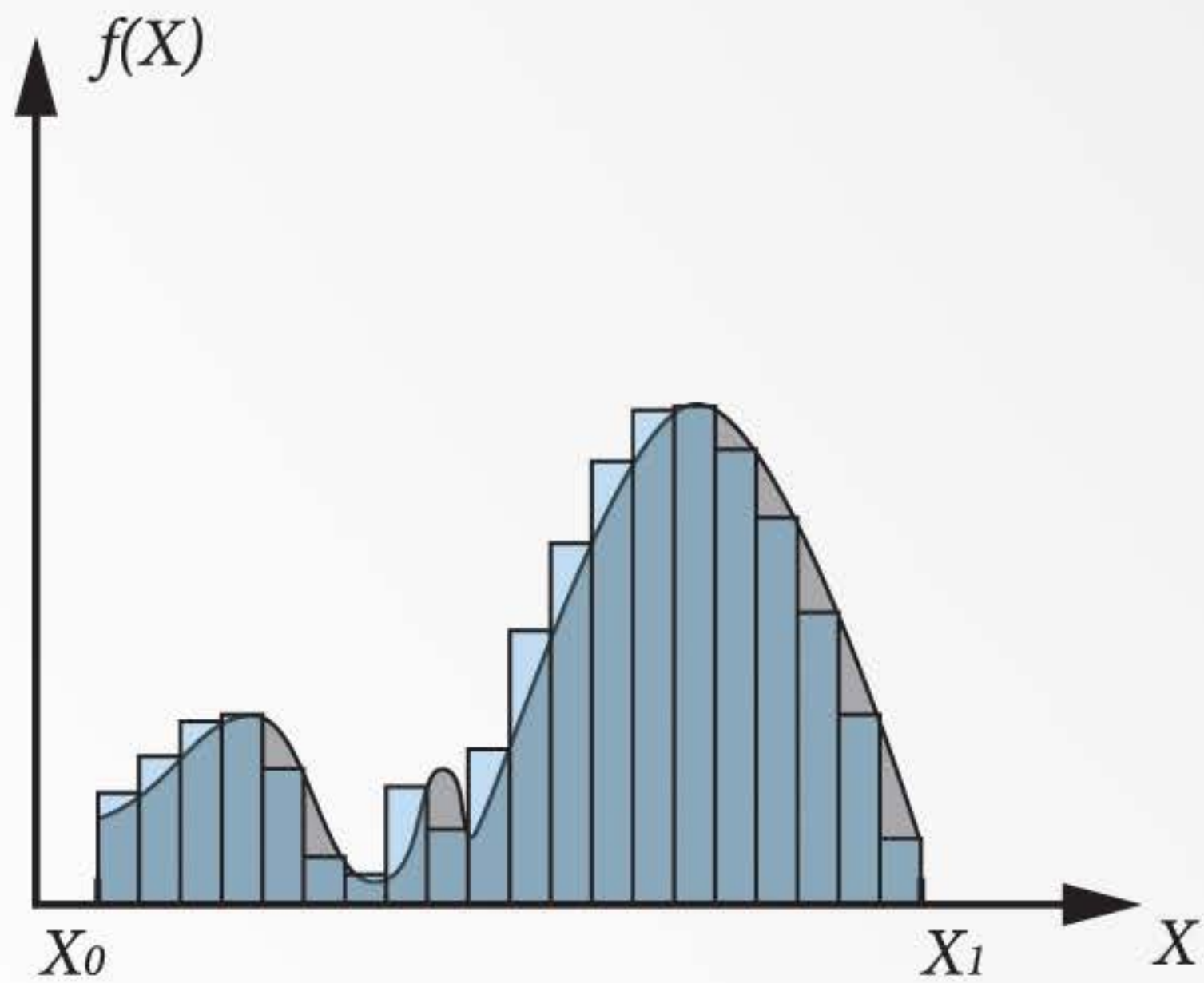


# 1D Integration with MC

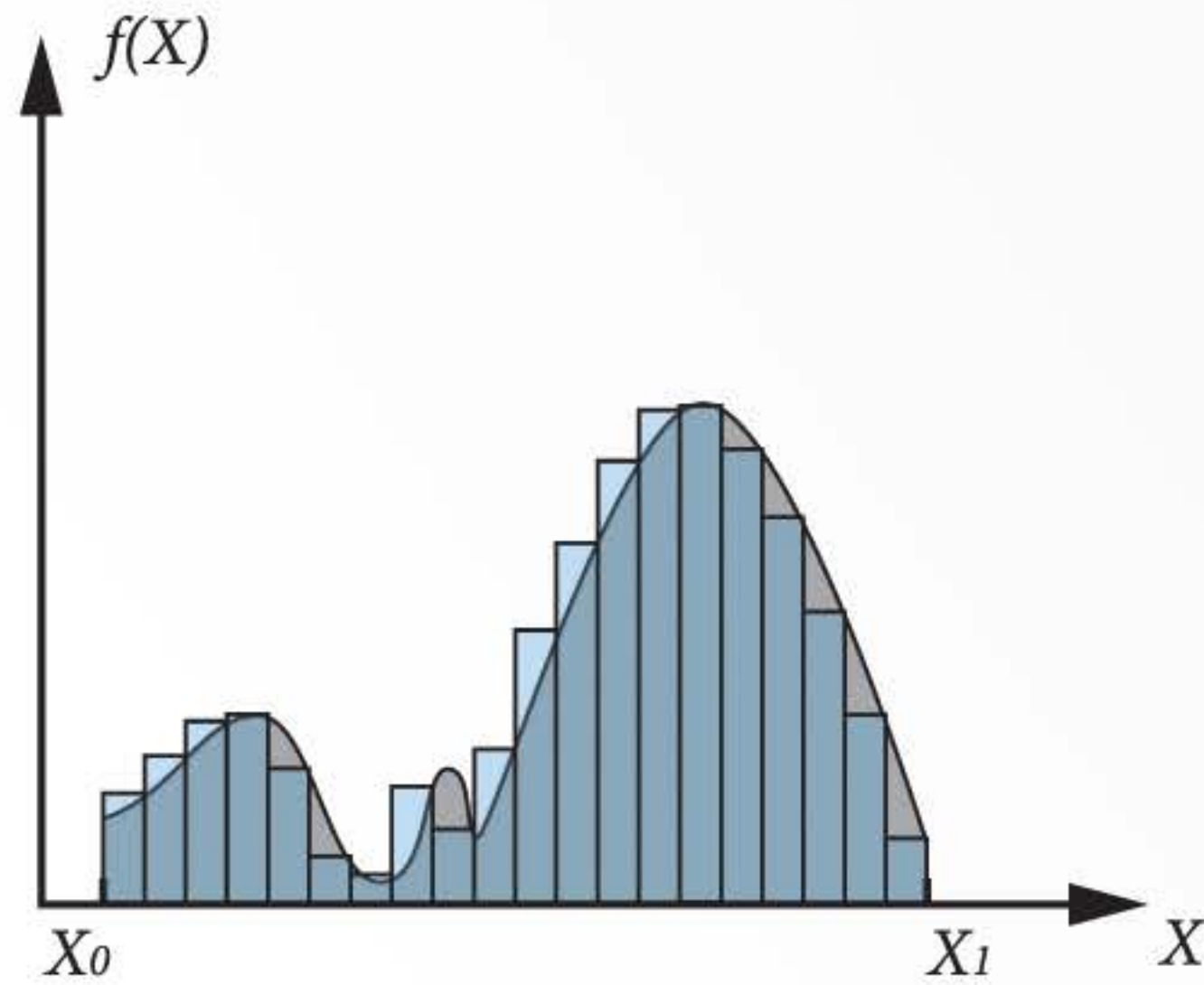




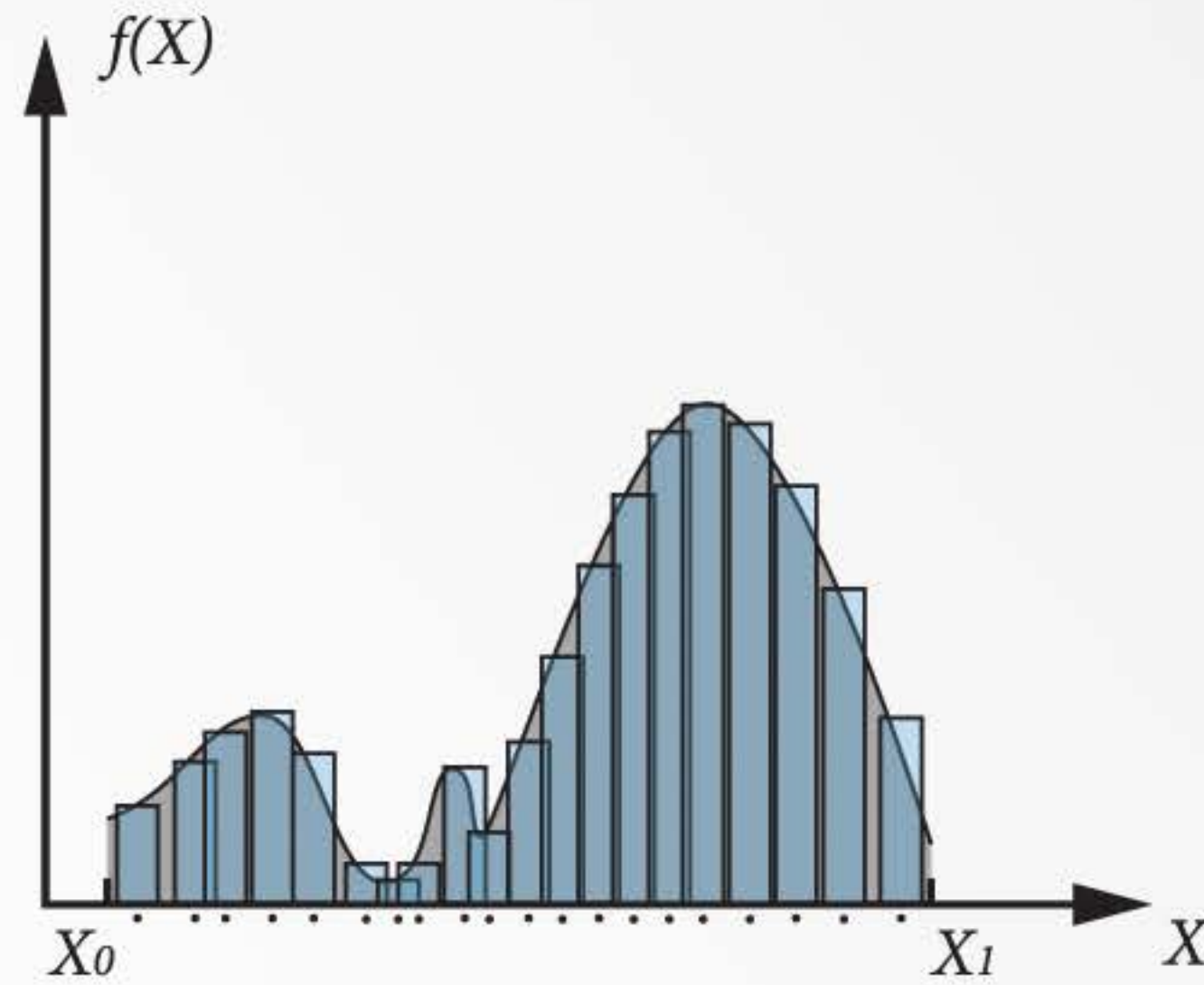
# 1D Integration with MC



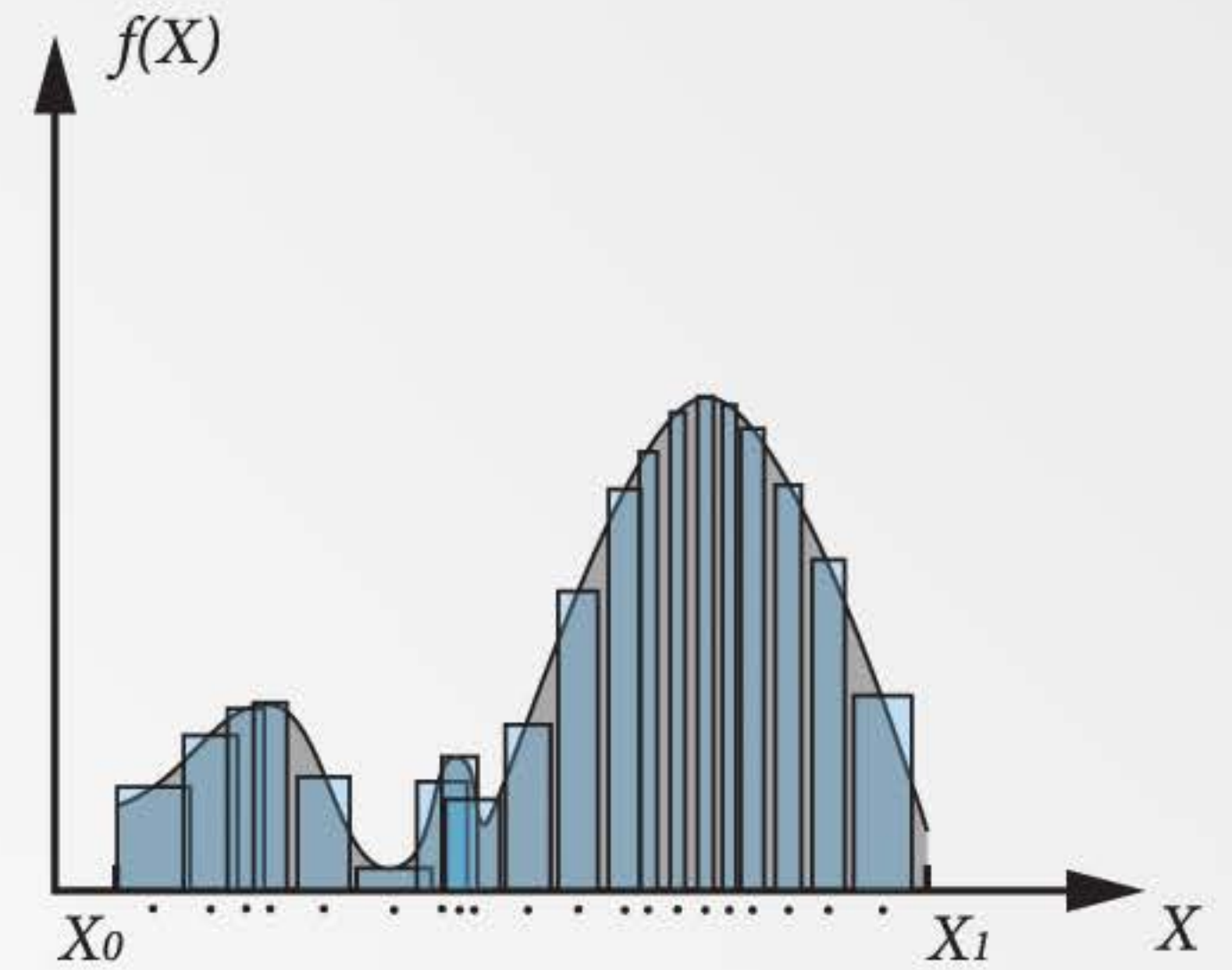
# 1D Integration with MC



Regular binning



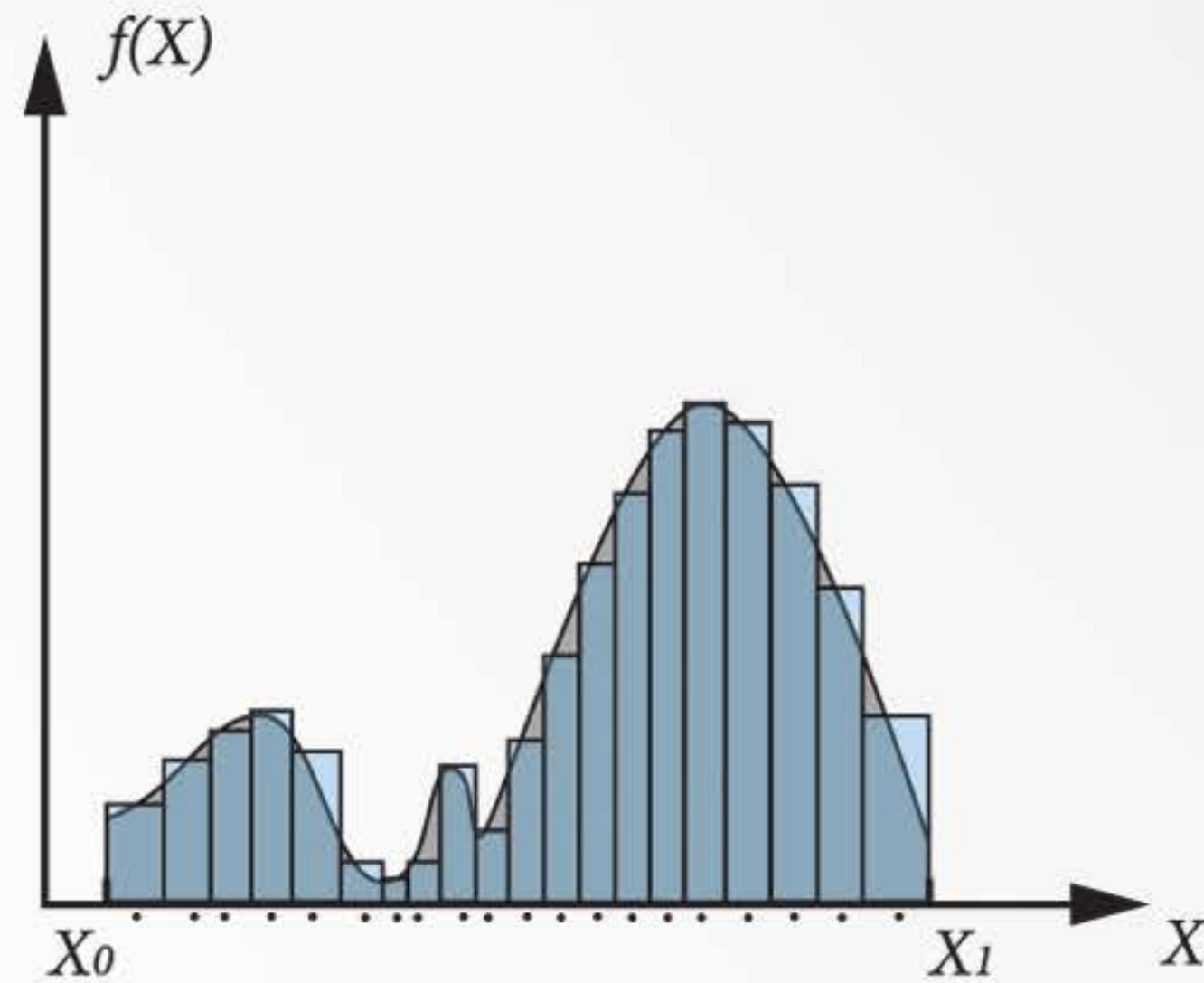
MC w/ random samples



MC w/ importance sampling



# 1D Integration with MC

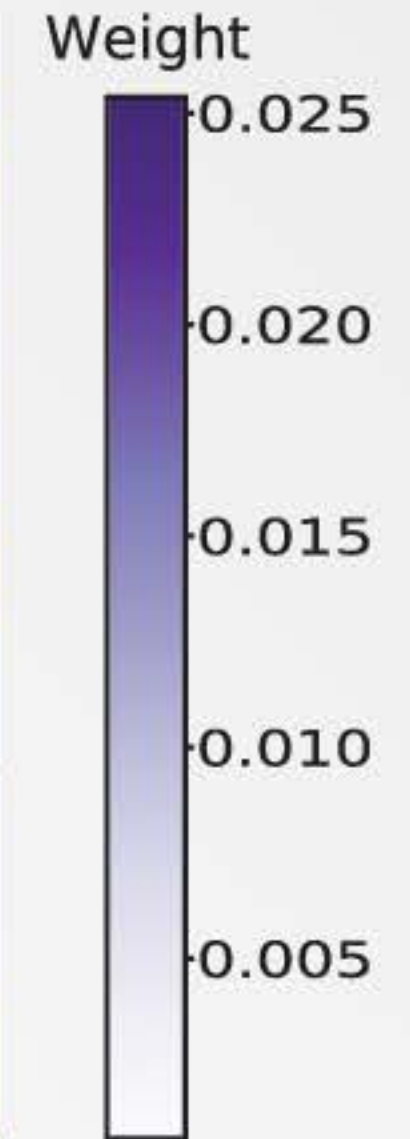
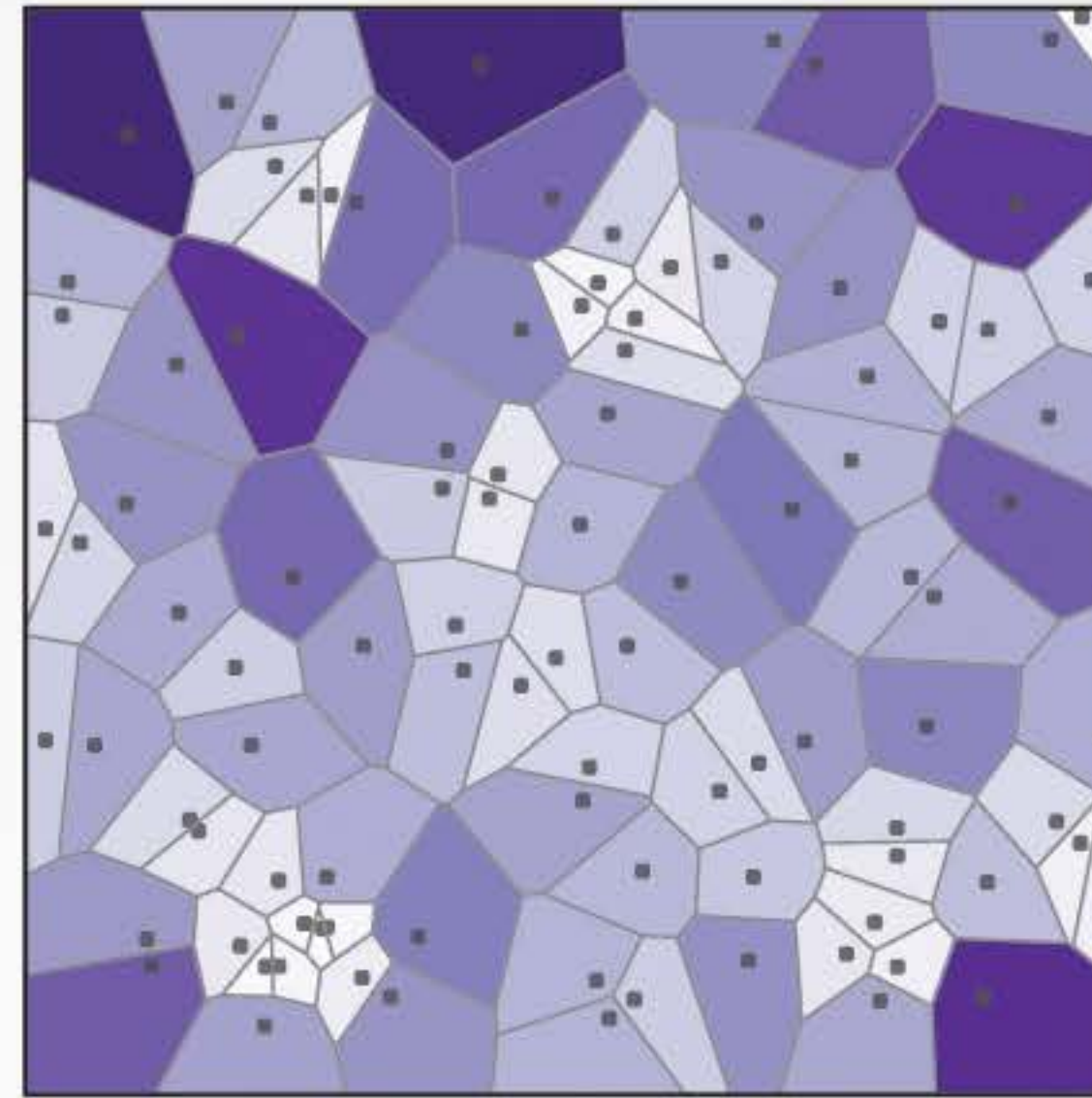
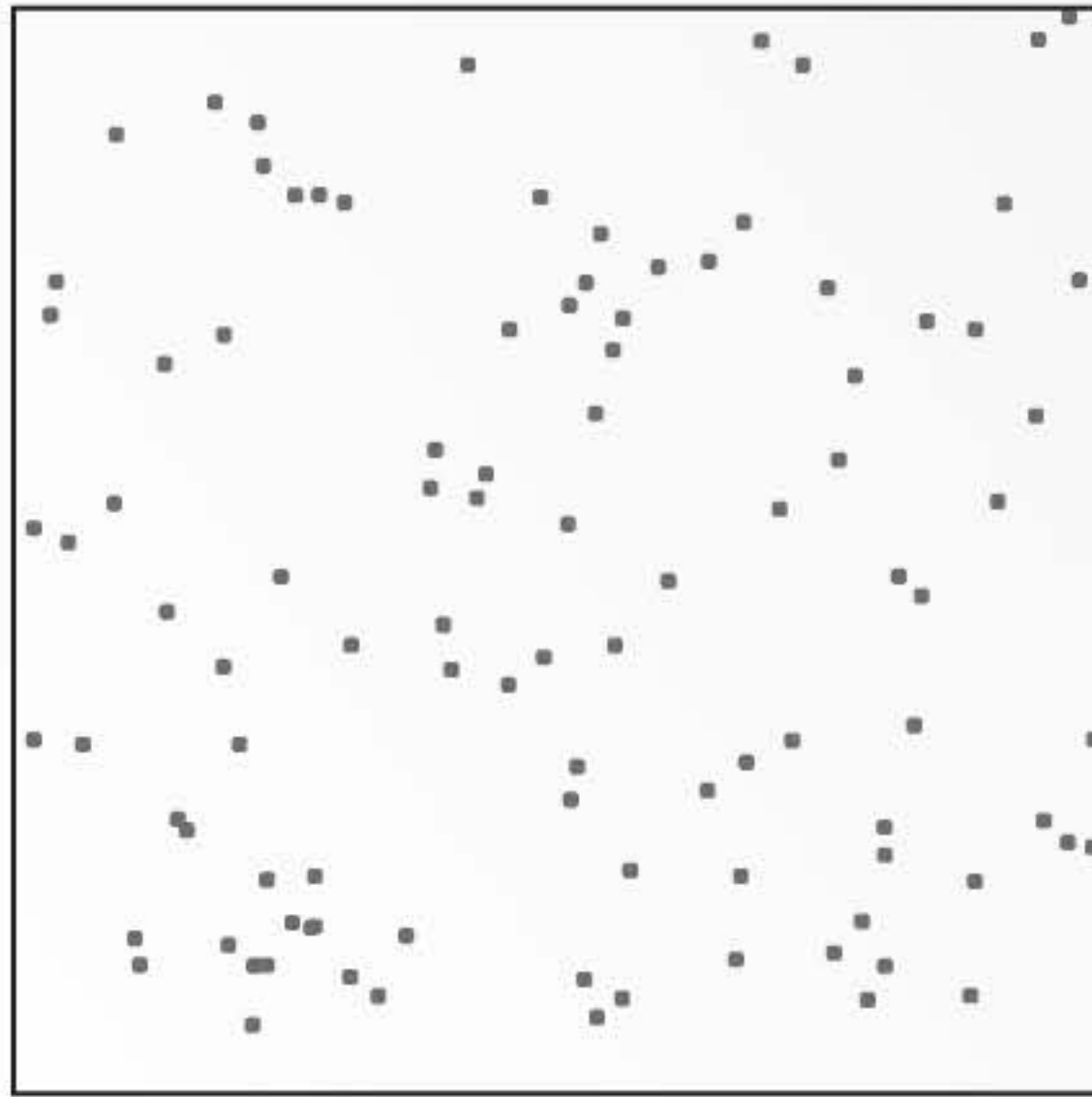


MC w/ reweighted  
random samples





# 1D Integration with MC



## 1D Integration with MC

$$\hat{I}_C = \sum_{i=1}^N w_C(x_i) f(x_i), \text{ where } w_C(x_i) = \frac{|V_i|}{|\Omega|}$$



# 1D Integration with MC

$$X = \{x_1, x_2, x_3\}, x_i \in (0, 1), x_1 < x_2 < x_3$$





# 1D Integration with MC



$$X = \{x_1, x_2, x_3\}, x_i \in (0, 1), x_1 < x_2 < x_3$$



# 1D Integration with MC

$$E[x_1] = \frac{1}{4}, E[x_2] = \frac{2}{4}, E[x_3] = \frac{3}{4}$$



# 1D Integration with MC

$$E[w_C(x_1)] = \frac{3}{8}, E[w_C(x_2)] = \frac{2}{8}, E[w_C(x_3)] = \frac{3}{8}$$





# 1D Integration with MC

$$\hat{I}_C = \sum_{i=1}^N w_C(x_i) f(x_i), \text{ where } w_C(x_i) = \frac{|V_i|}{|\Omega|}$$

**BIASED**



# Contribution

Unbiased solution to 1D uniform reweighting

Start from definition

$$E[\hat{I}] = \lim_{N \rightarrow \infty} \frac{1}{N} \sum_{i=1}^N f(x_i) = \int f(x) dx$$



# Contribution

Unbiased solution to 1D uniform reweighting





# Contribution

Unbiased solution to 1D uniform reweighting

Start from definition

Prove what we already know



# Start from Definition

$$\|\{x\}\| = N$$

$$\mathbb{F}(\{x\}) = \frac{1}{N} \sum_{i=1}^N \frac{f(x_i)}{p(x_i)}$$



# Start from Definition

$$E \left[ \frac{1}{N} \sum_{i=1}^N \frac{f(x_i)}{p(x_i)} \right] = E [\mathbb{F}(\{x\})]$$





# Start from Definition

$$\mathbb{P}(\{x\}) = N! \prod_{i=1}^N p(x_i)$$

$$p(x_i) = 1$$



## Start from Definition

$$E[\mathbb{F}(\{x\})] = \int \mathbb{F}(\{x\})\mathbb{P}(\{x\})d\{x\} = \int \mathbb{F}(\{x\})d\{x\}$$



## Start from Definition

$$\begin{aligned}\mathbb{E} [\hat{I}_{MC}] &= \int_{(0,1)^N} \mathbb{F}(\{x_i\}) P(\{x_i\}) d\{x_i\} \\ &= \int_0^1 \int_0^1 \cdots \int_0^1 \left[ \sum_{i=1}^N \frac{1}{N} \frac{f(x_i)}{p(x_i)} \right] N! \prod_{i=1}^N p(x_i) d\{x_i\} \\ &= \int_0^1 \int_{x_1}^1 \cdots \int_{x_{N-1}}^1 \left[ \sum_{i=1}^N \frac{1}{N} f(x_i) \right] N! d\{x_i\} \\ &= N! \int_0^1 \int_{x_1}^1 \cdots \int_{x_{N-1}}^1 \\ &\quad \left[ \frac{1}{N} f(x_1) + \frac{1}{N} f(x_2) + \cdots + \frac{1}{N} f(x_N) \right] dx_N dx_{N-1} \cdots dx_1\end{aligned}$$





## Start from Definition

$$\int_0^1 \int_{x_1}^1 \cdots \int_{x_{N-1}}^1 dx_N dx_{N-1} \cdots dx_1 = \int_0^1 \int_0^{x_N} \cdots \int_0^{x_2} dx_1 dx_2 \cdots dx_N$$



## Start from Definition

$$\int_0^{x_{i+1}} \int_0^{x_i} \cdots \int_0^{x_2} dx_1 dx_2 \cdots dx_i = \frac{x_{i+1}^i}{i!},$$
$$\int_{x_{i-1}}^1 \int_{x_i}^1 \cdots \int_{x_{N-1}}^1 dx_N dx_{N-1} \cdots dx_i = \frac{(1 - x_{i-1})^{N-i+1}}{(N - i + 1)!}.$$



## Start from Definition

$$\begin{aligned}\mathbb{E} [\hat{I}_{MC}] &= N! \int_0^1 \int_{x_1}^1 \cdots \int_{x_{N-1}}^1 \\ &\quad \left[ \frac{1}{N} f(x_1) + \frac{1}{N} f(x_2) + \cdots + \frac{1}{N} f(x_N) \right] dx_N dx_{N-1} \cdots dx_1 \\ &= N! \cdot \frac{1}{N} \left[ \int_0^1 f(x_1) \int_{x_1}^1 \cdots \int_{x_{N-1}}^1 dx_N \cdots dx_2 dx_1 + \cdots \right. \\ &\quad \left. + \int_0^1 \cdots \int_{x_{i-1}}^1 f(x_i) \cdots \int_{x_{N-1}}^1 dx_N dx_{N-1} \cdots dx_1 + \cdots \right. \\ &\quad \left. + \int_0^1 \int_{x_1}^1 \cdots \int_{x_{N-1}}^1 f(x_N) dx_N dx_{N-1} \cdots dx_1 \right]\end{aligned}$$



## Start from Definition

$$\begin{aligned} &= N! \cdot \frac{1}{N} \left[ \int_0^1 \frac{(1-x_1)^{N-1}}{(N-1)!} f(x_1) dx_1 + \dots \right. \\ &\quad + \int_{x_{i-1}}^1 \frac{x_i^{i-1}}{(i-1)!} \frac{(1-x_i)^{N-i}}{(N-i)!} f(x_i) dx_i + \dots \\ &\quad \left. + \int_{x_{N-1}}^1 \frac{x_N^{N-1}}{(N-1)!} f(x_N) dx_N \right] \end{aligned}$$





## Start from Definition

$$\begin{aligned} &= N! \cdot \frac{1}{N} \left[ \int_0^1 \frac{(1-x)^{N-1}}{(N-1)!} f(x) dx + \cdots + \right. \\ &\quad \int_0^1 \frac{x^{i-1}}{(i-1)!} \frac{(1-x)^{N-i}}{(N-i)!} f(x) dx + \cdots \\ &\quad \left. + \int_0^1 \frac{x^{N-1}}{(N-1)!} f(x) dx \right] \end{aligned}$$



## Start from Definition

$$\begin{aligned} &= N! \cdot \frac{1}{N} \int_0^1 \sum_{i=1}^N \frac{x^{i-1}}{(i-1)!} \frac{(1-x)^{N-i}}{(N-i)!} f(x) dx \\ &= \int_0^1 \sum_{i=1}^N \frac{(N-1)!}{(i-1)!(N-i)!} x^{i-1} (1-x)^{N-i} f(x) dx \end{aligned}$$



## Start from Definition

$$= \int_0^1 [x + (1-x)]^{N-1} \cdot f(x) dx = \int_0^1 f(x) dx.$$



# Integrating the Consistent Reweighting Estimator

Repeating the same process





# Integrating the Consistent Reweighting Estimator

$$\begin{aligned} \mathbb{E} [\hat{I}_C] = & N! \int_0^1 \int_{x_1}^1 \cdots \int_{x_{N-1}}^1 \\ & \left[ \frac{x_1 + x_2}{2} f(x_1) + \sum_{i=2}^{N-1} \frac{x_{i+1} - x_{i-1}}{2} f(x_i) + \right. \\ & \left. \left( 1 - \frac{x_{N-1} + x_N}{2} \right) f(x_N) \right] dx_N dx_{N-1} \cdots dx_1 \end{aligned}$$



# Integrating the Consistent Reweighting Estimator

$$\begin{aligned}
 &= N! \cdot \int_0^1 \left\{ \frac{1}{2} \cdot \frac{x \cdot (1-x)^{N-1}}{(N-1)!} + \frac{1}{2} \cdot \frac{(1-x)^{N-1} [(N-1) \cdot x + 1]}{N!} \right. \\
 &\quad + \sum_{i=2}^{N-1} \left[ \frac{1}{2} \cdot \frac{(1-x)^{N-i} [(N-i) \cdot x + 1] \cdot x^{i-1}}{(N-i+1)!(i-1)!} - \frac{1}{2} \cdot \frac{(1-x)^{N-i} \cdot x^i}{i(N-i)!(i-2)!} \right] \\
 &\quad \left. + \left[ \frac{x^{N-1}}{(N-1)!} - \frac{1}{2} \cdot \frac{x^N}{N(N-2)!} - \frac{1}{2} \cdot \frac{x^N}{(N-1)!} \right] \right\} \cdot f(x) dx
 \end{aligned}$$

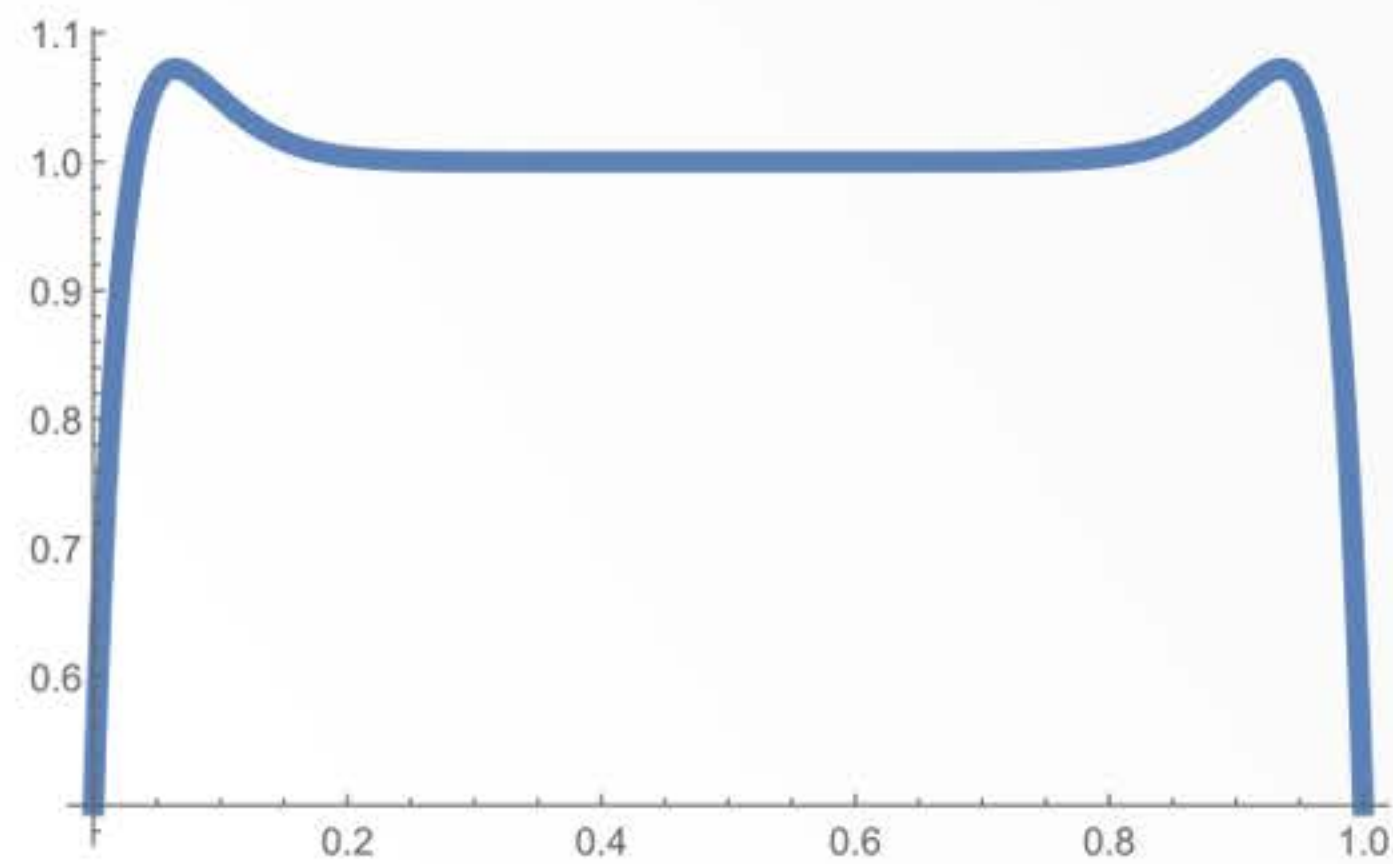


# Integrating the Consistent Reweighting Estimator

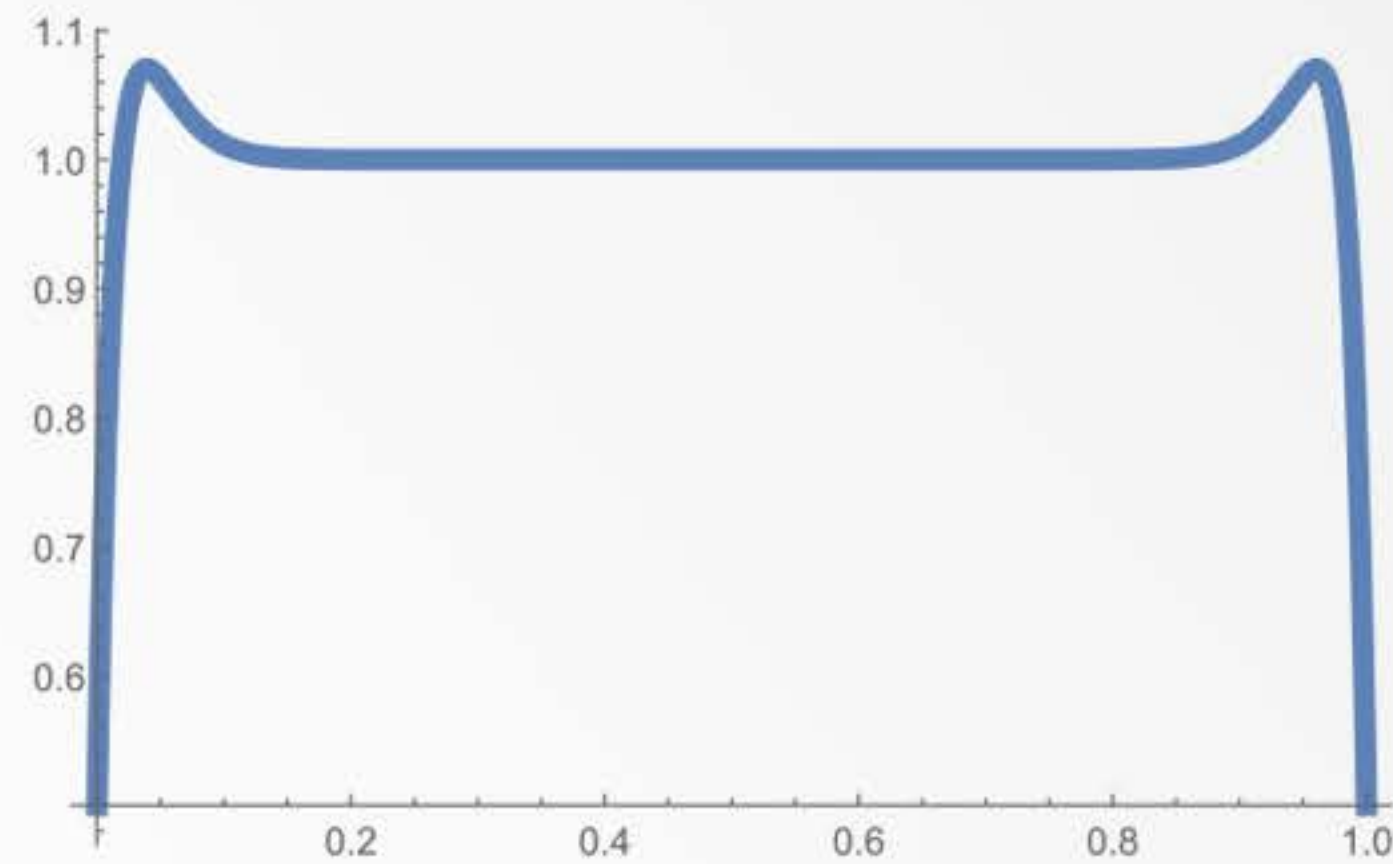
$$= \int_0^1 \frac{(N - Nx - x)x^{N-1} + (Nx + x - 1)(1 - x)^{N-1} + 2}{2} \cdot f(x) dx$$



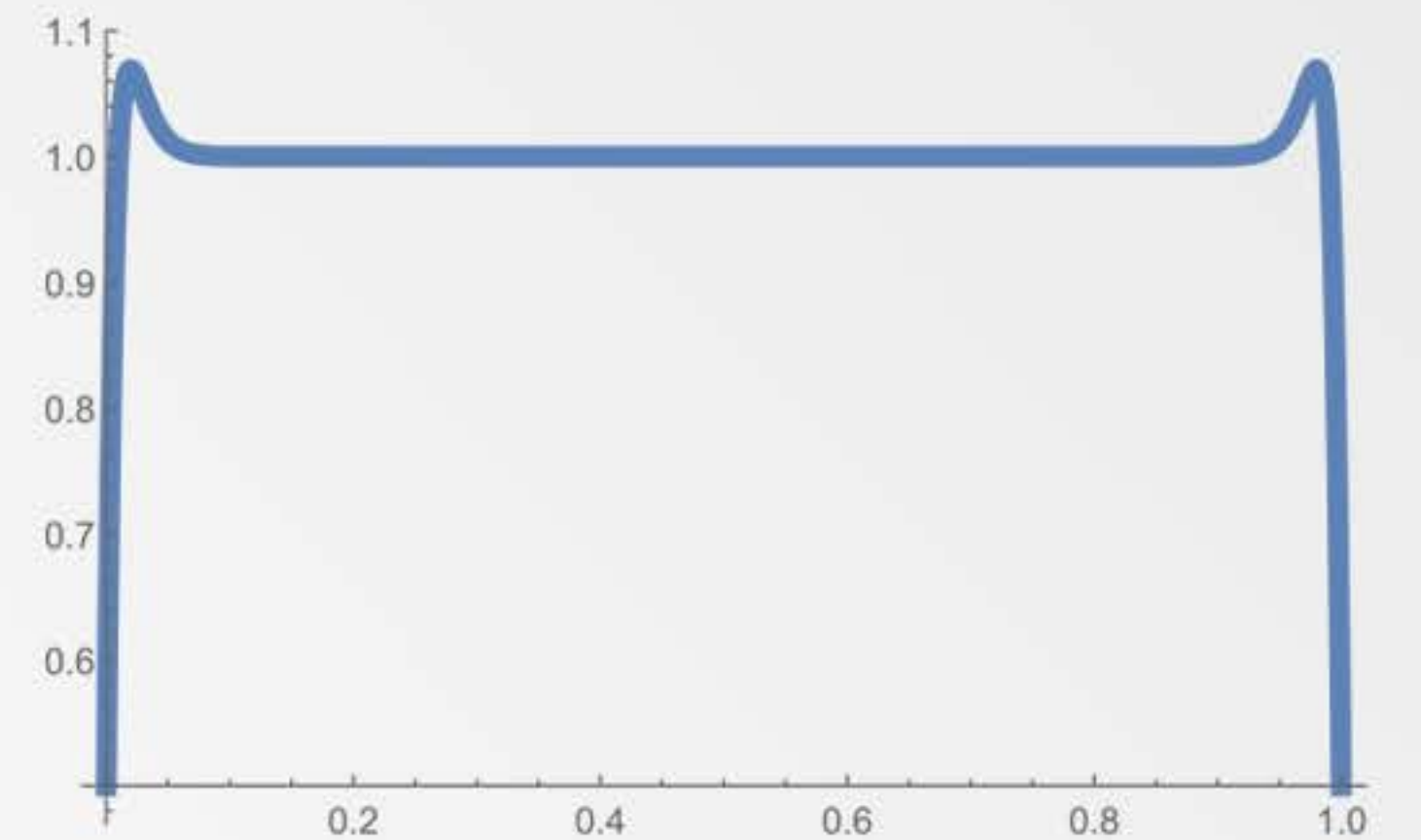
# Integrating the Consistent Reweighting Estimator



N=30



N=50



N=100





# Integrating the Consistent Reweighting Estimator

$$g(x) = \frac{(N - Nx - x)x^{N-1} + (Nx + x - 1)(1 - x)^{N-1} + 2}{2}$$



# Integrating the Consistent Reweighting Estimator

$$E[\mathbb{F}(\{x\})] = \int g(x)f(x)dx$$



# Deriving the Unbiased Reweighting Estimator

$$\begin{aligned}\mathbb{E} \left[ \hat{I}_C^F \right] &= \int_0^1 g(x) \cdot F(x) dx = \int_0^1 g(x) \cdot \frac{f(x)}{g(x)} dx \\ &= \int_0^1 f(x) dx = \mathbb{E} \left[ \hat{I} \right].\end{aligned}$$



# Deriving the Unbiased Reweighting Estimator

$$\hat{I}_{GR} = \sum_{i=1}^N w_{GR}(x_i) f(x_i) = \sum_{i=1}^N \frac{|V_i|}{|\Omega|} \frac{1}{g(x_i)} f(x_i)$$





# Numerical Performance

1D Unbiased & 2D Consistent



# Numerical Performance

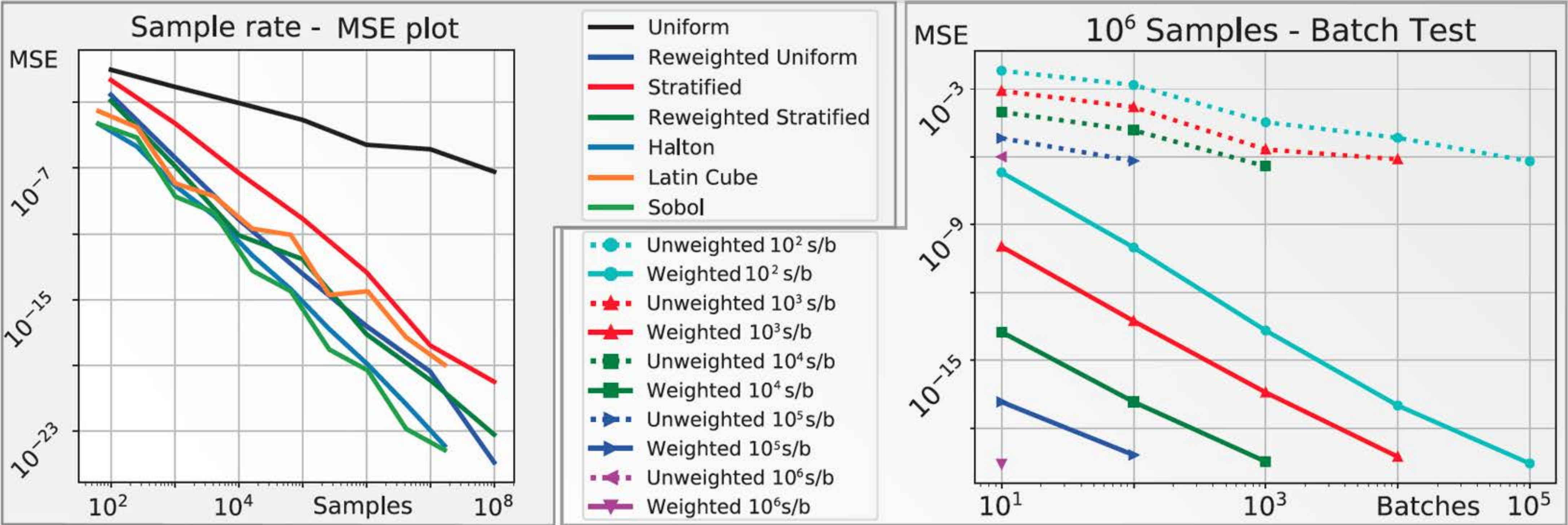
$$f(x) = 10 \times \begin{cases} \sqrt{-x^2 + 0.5x} & x \leq 0.25 \\ -\sqrt{-x^2 + x - 0.1875} + 0.25 & 0.25 < x \leq 0.5 \\ 20 \times (x - 0.5) & 0.5 < x \leq 0.55 \\ 1.0 & 0.55 < x \leq 0.65 \\ -20 \times (x - 0.7) & 0.65 < x \leq 0.7 \\ 0.1 \times \sin(10\pi \cdot (x - 0.7)) & 0.7 < x \leq 0.8 \\ 0.25 \times \sin(10\pi \cdot (x - 0.8)) & 0.8 < x \leq 0.9 \\ 0.5 \times \sin(10\pi \cdot (x - 0.9)) & 0.9 < x \end{cases}$$





# Numerical Performance

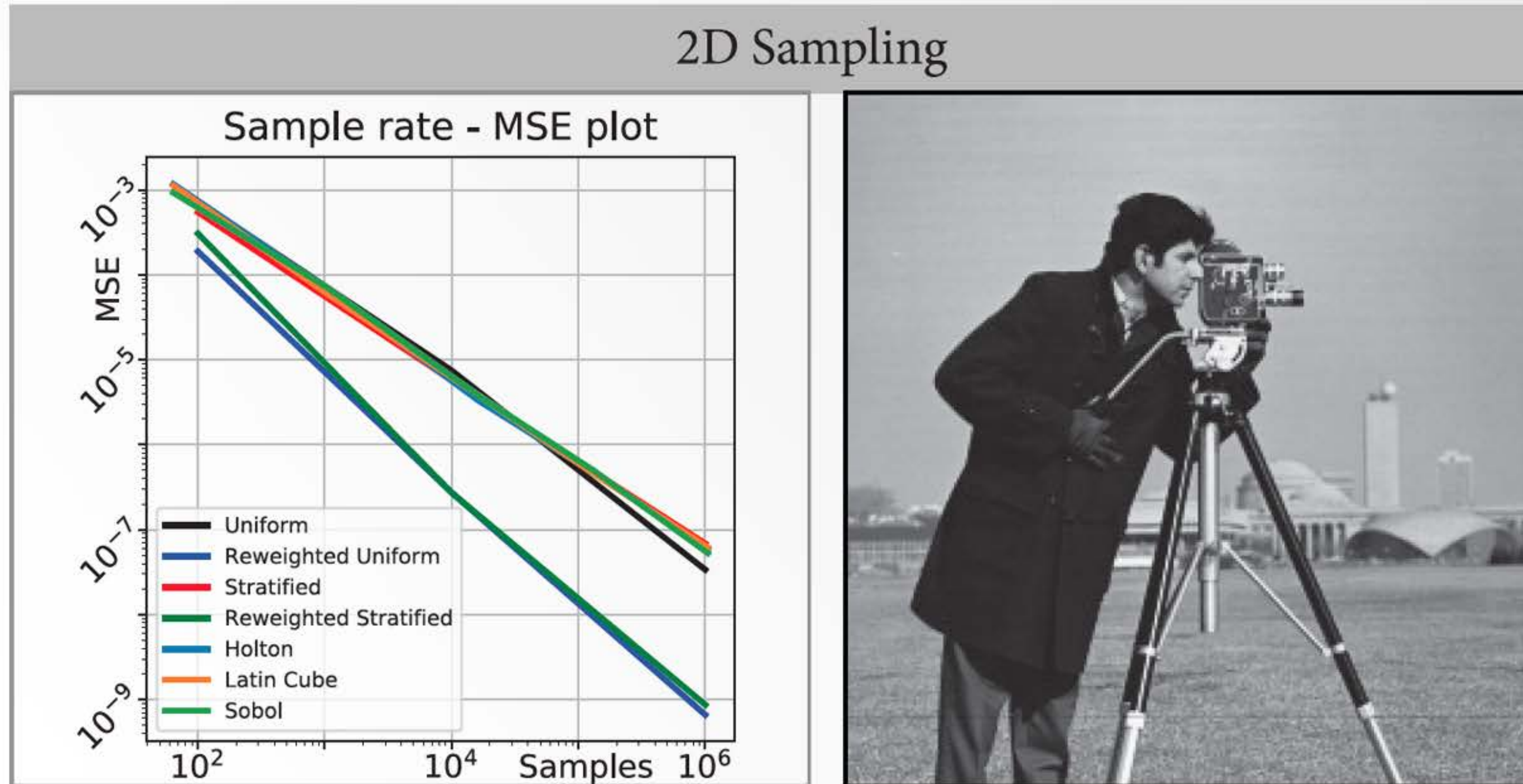
## 1D Sampling





# Numerical Performance

## 2D Sampling





# Numerical Performance

Unbiased solution for uniform samples

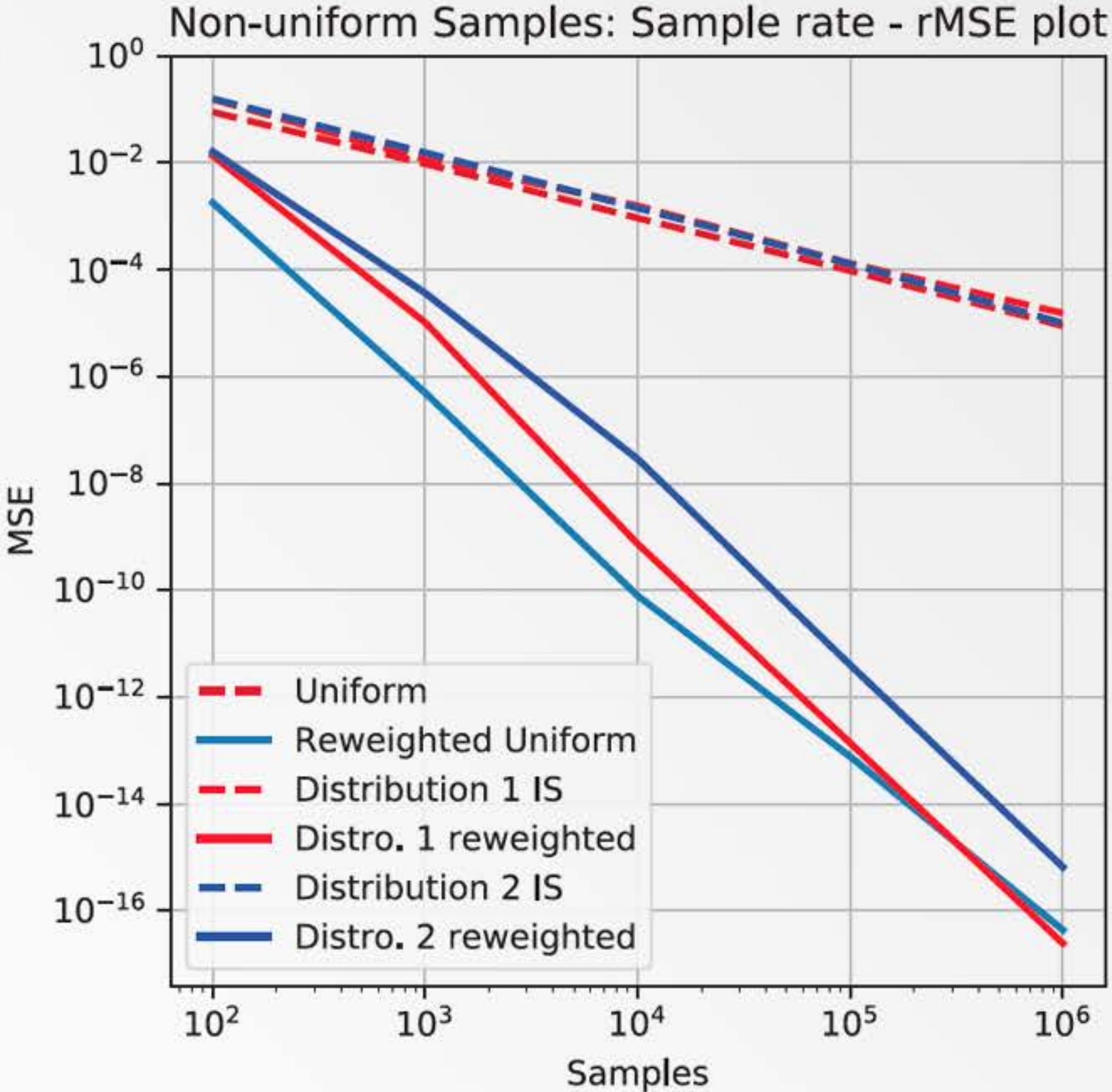
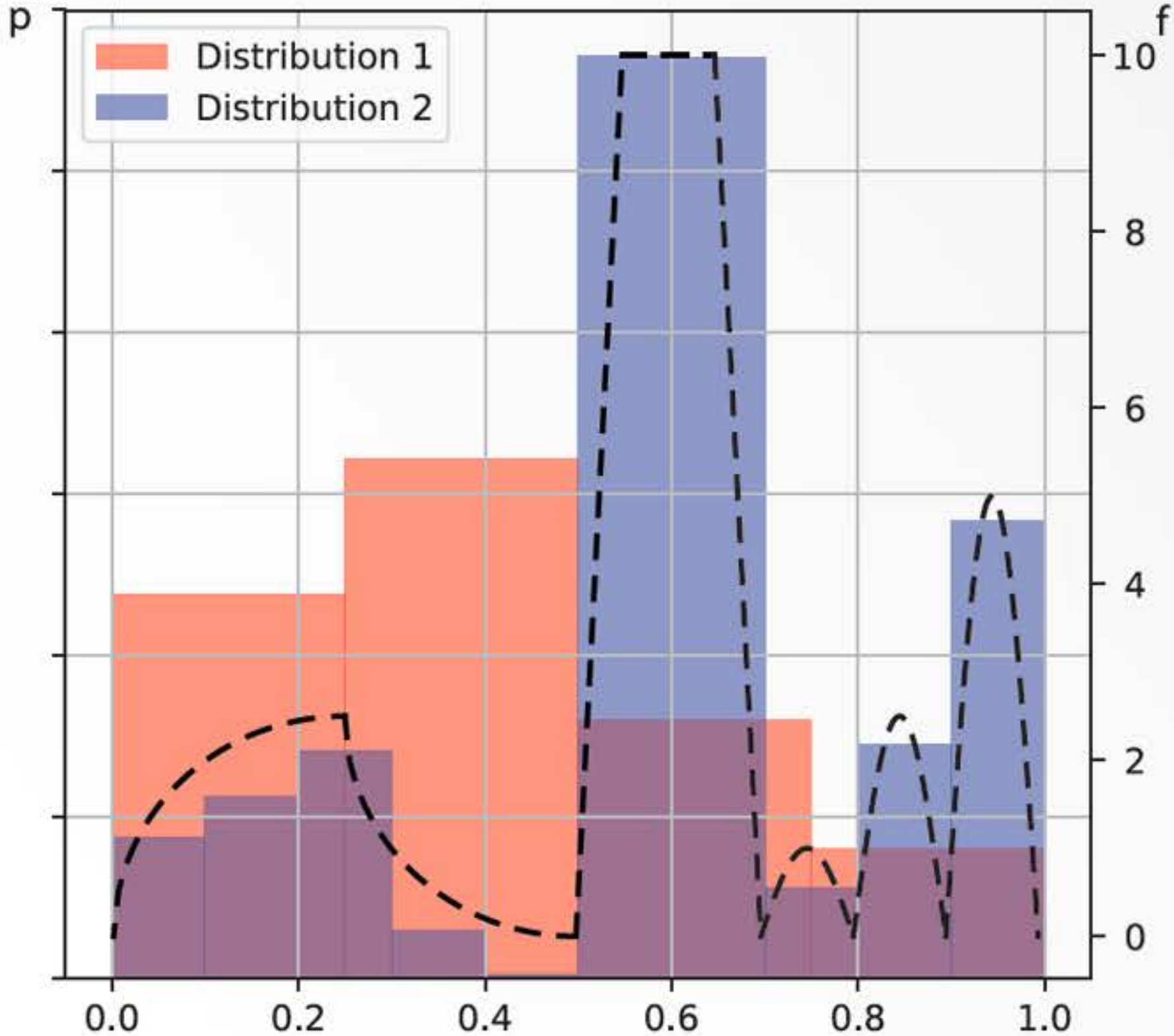
Unbiased solution for piece-wise uniform samples

Commonly used in computer graphics

Essentially a collection of uniform sample sets



# Numerical Performance



# Applying to Rendering

## Monte Carlo rendering problems

1D temporal sampling

1D spectral sampling

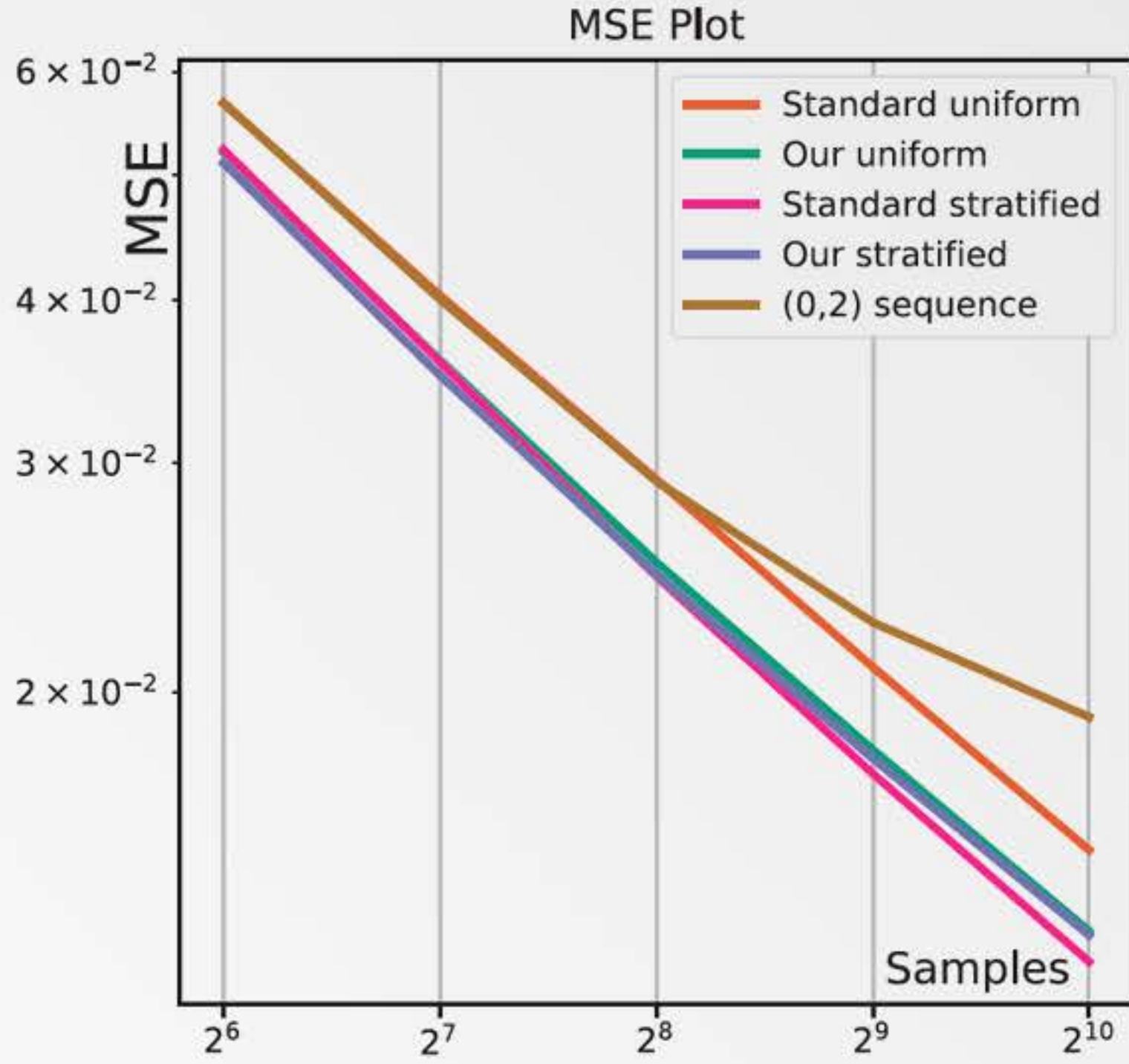
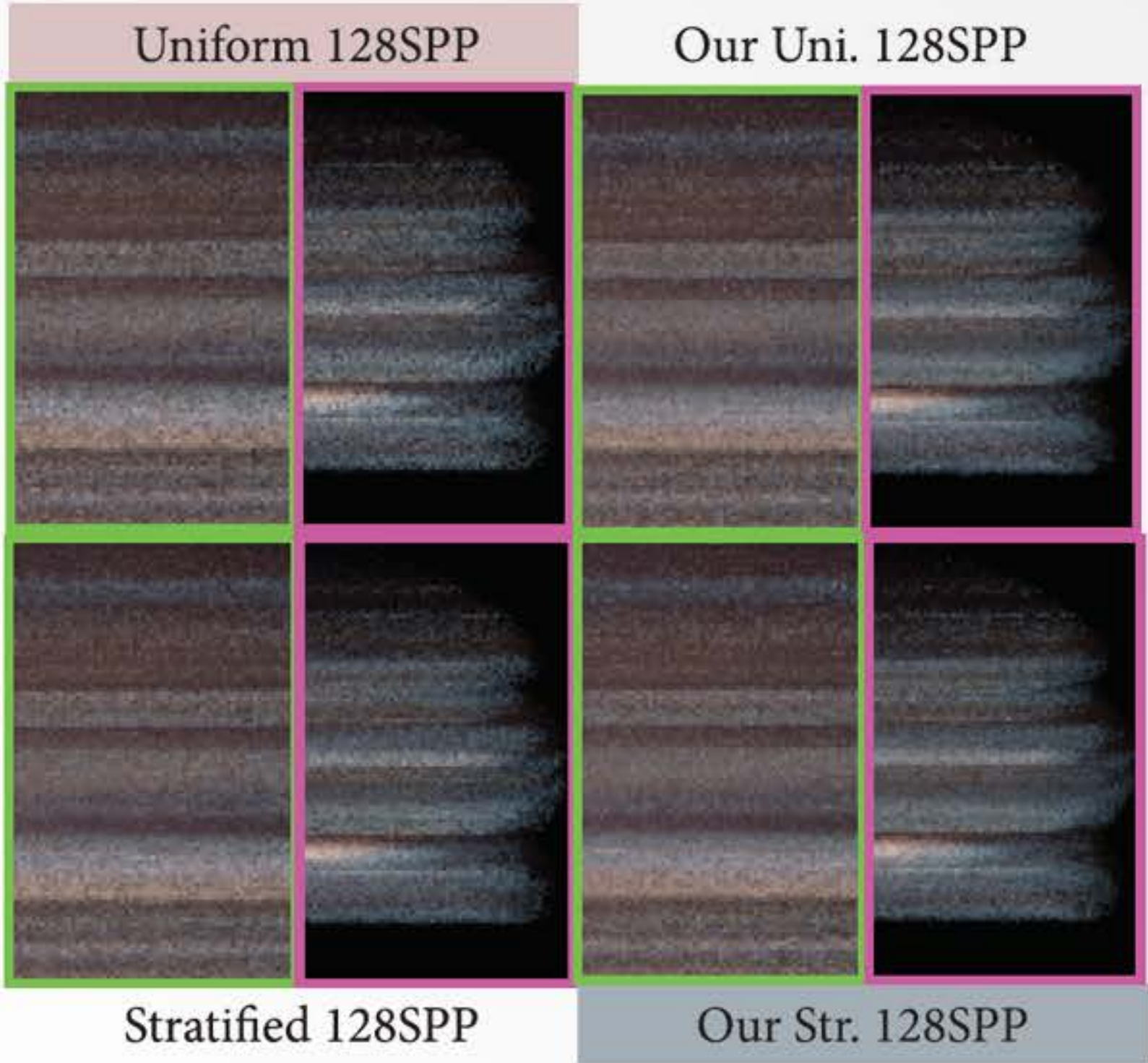
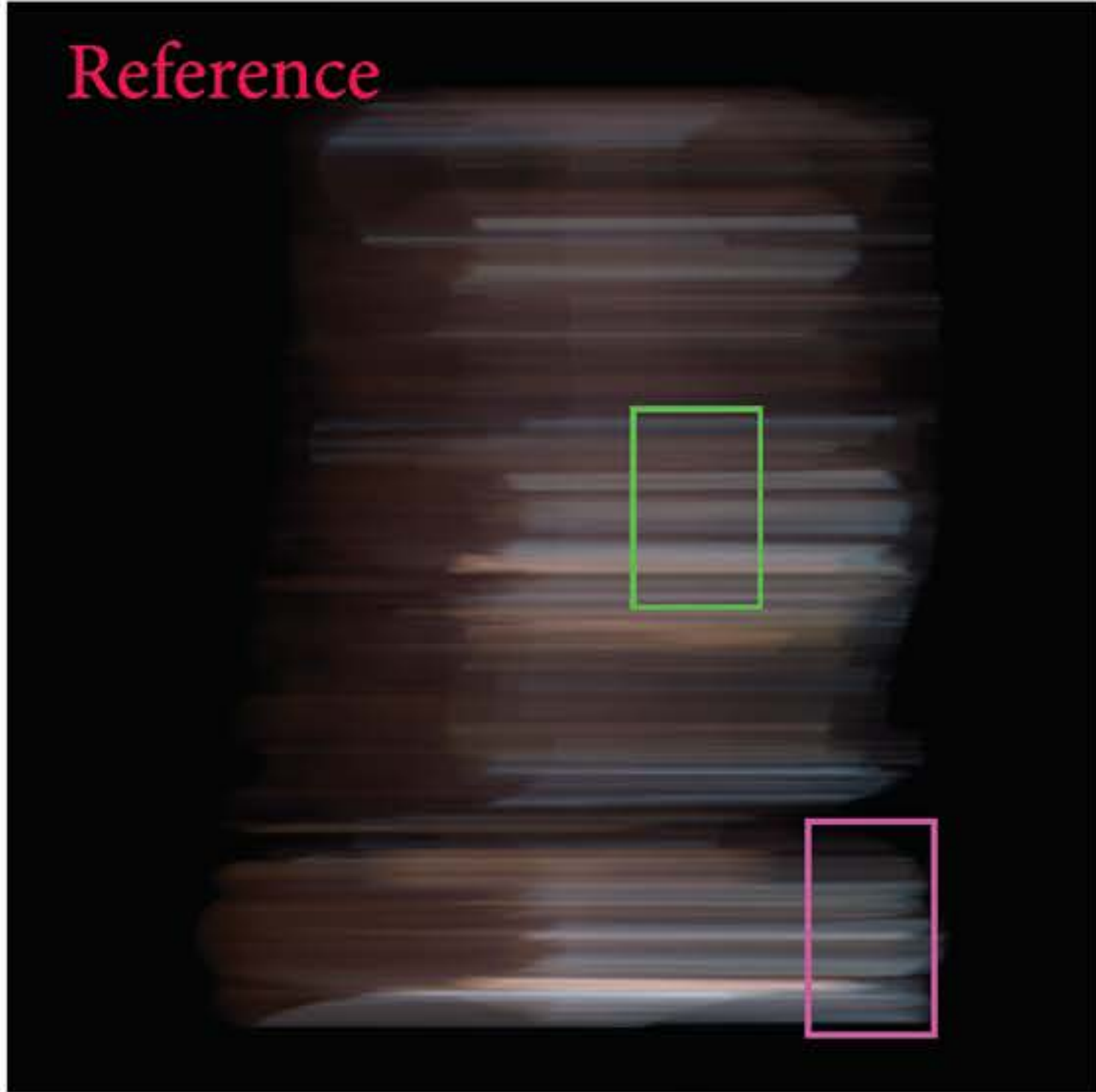
2D lens sampling

2D direct illumination sampling





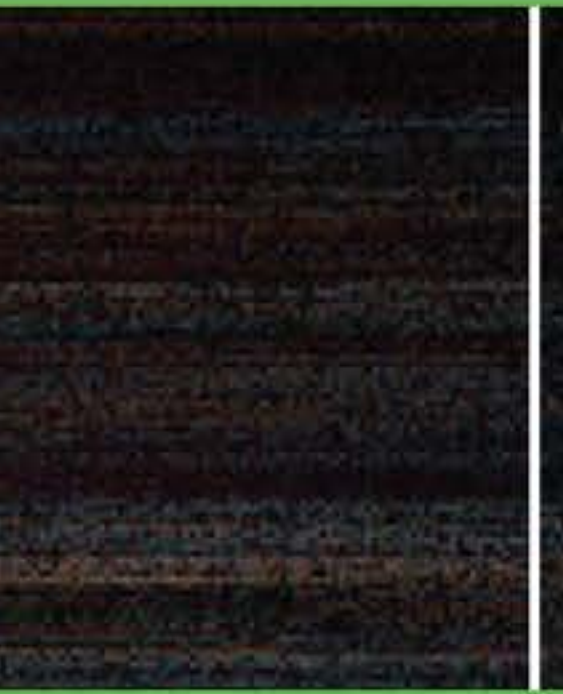

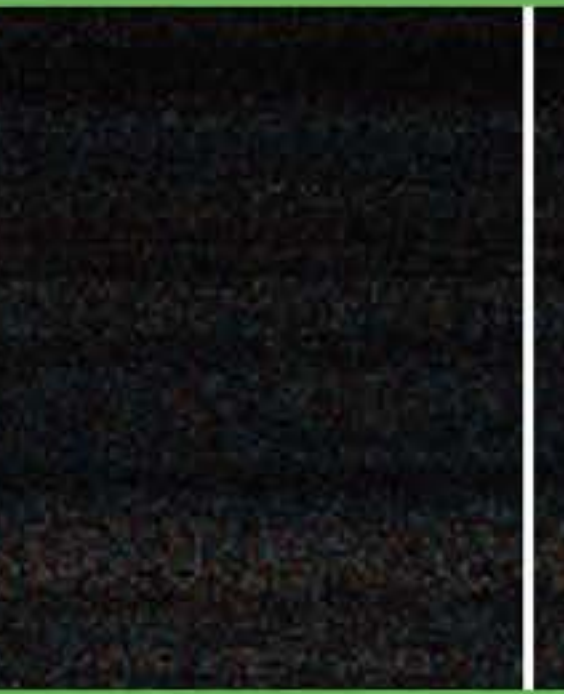


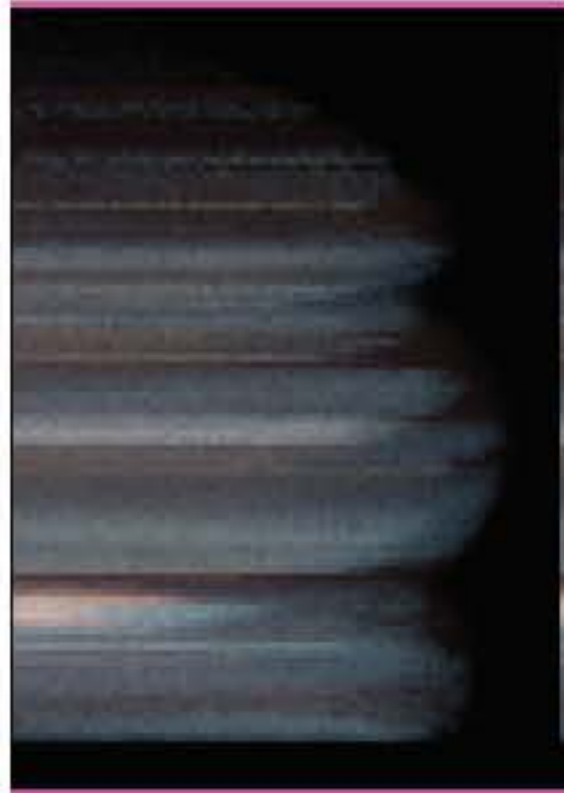








# Results





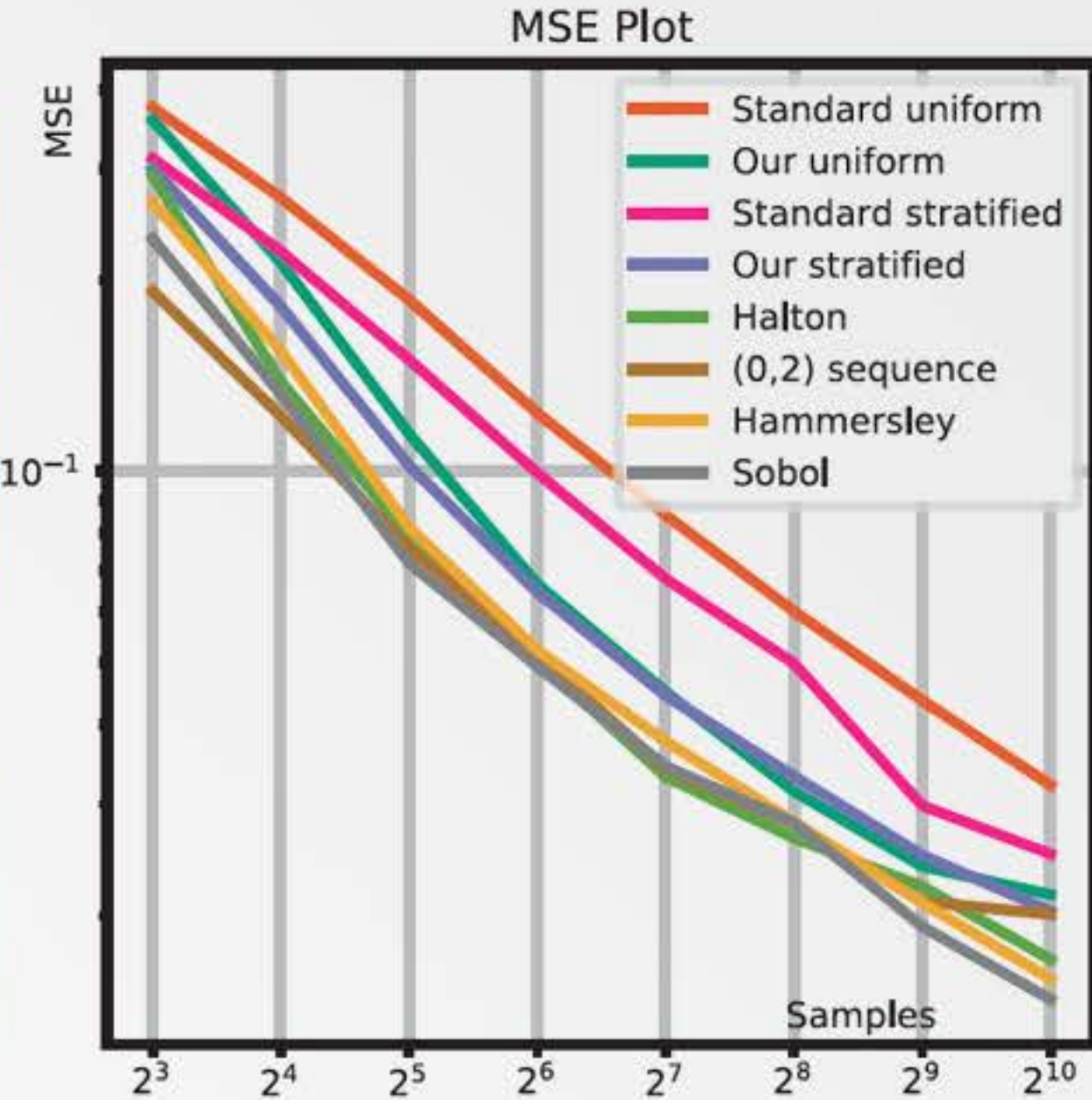
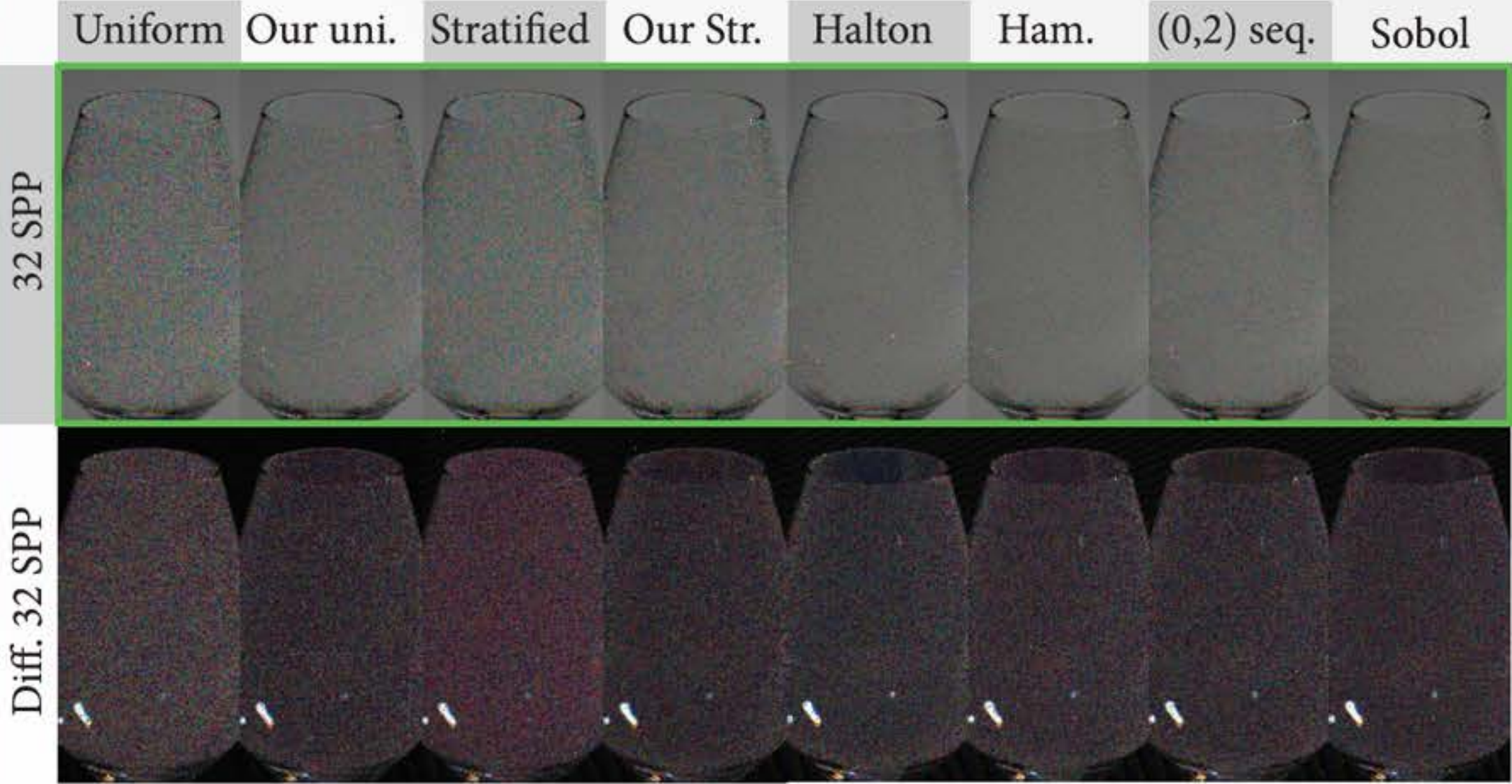
# Results

						
(0,2) seq. 512 SPP	(0,2) seq. 1024 SPP	Diff. 1K SPP (0,2) seq.	Diff. 1K SPP Uniform	Diff. 1K SPP Our uniform	Diff. 1K SPP Stratified	Diff. 1K SPP Our Str.
						



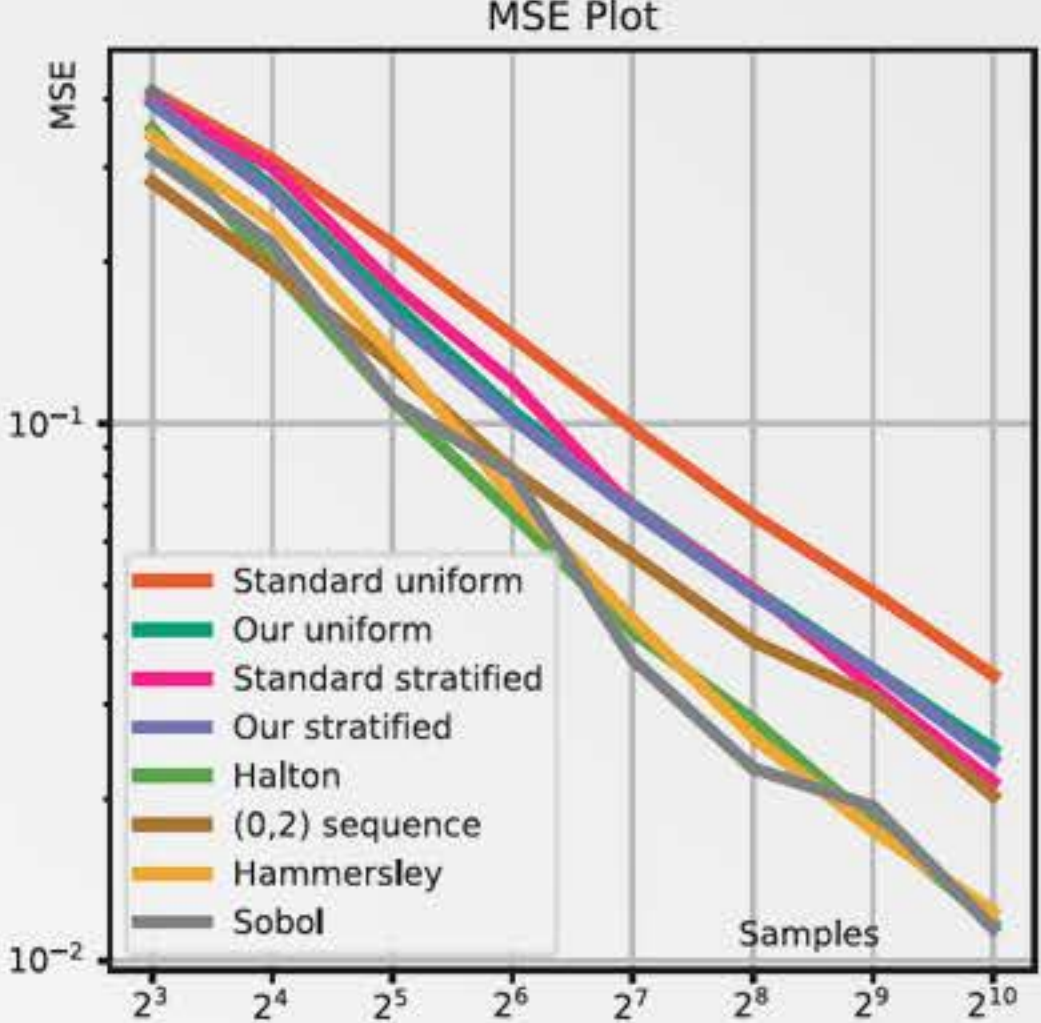
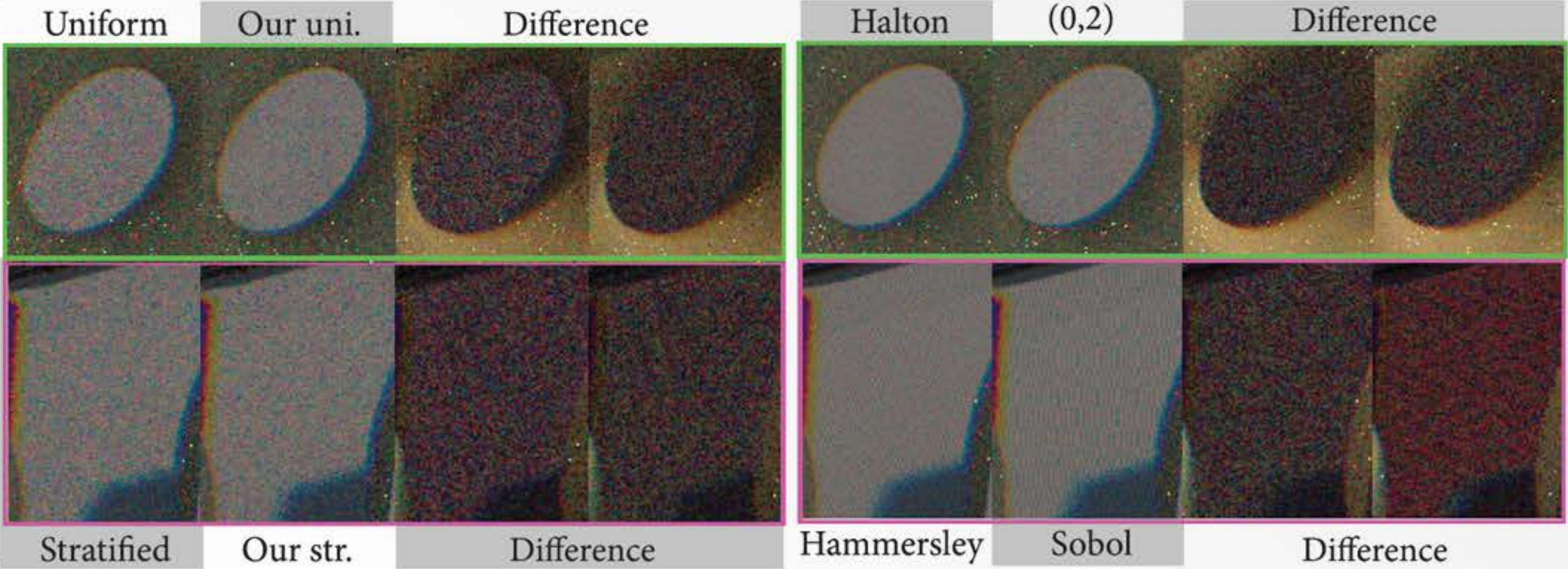
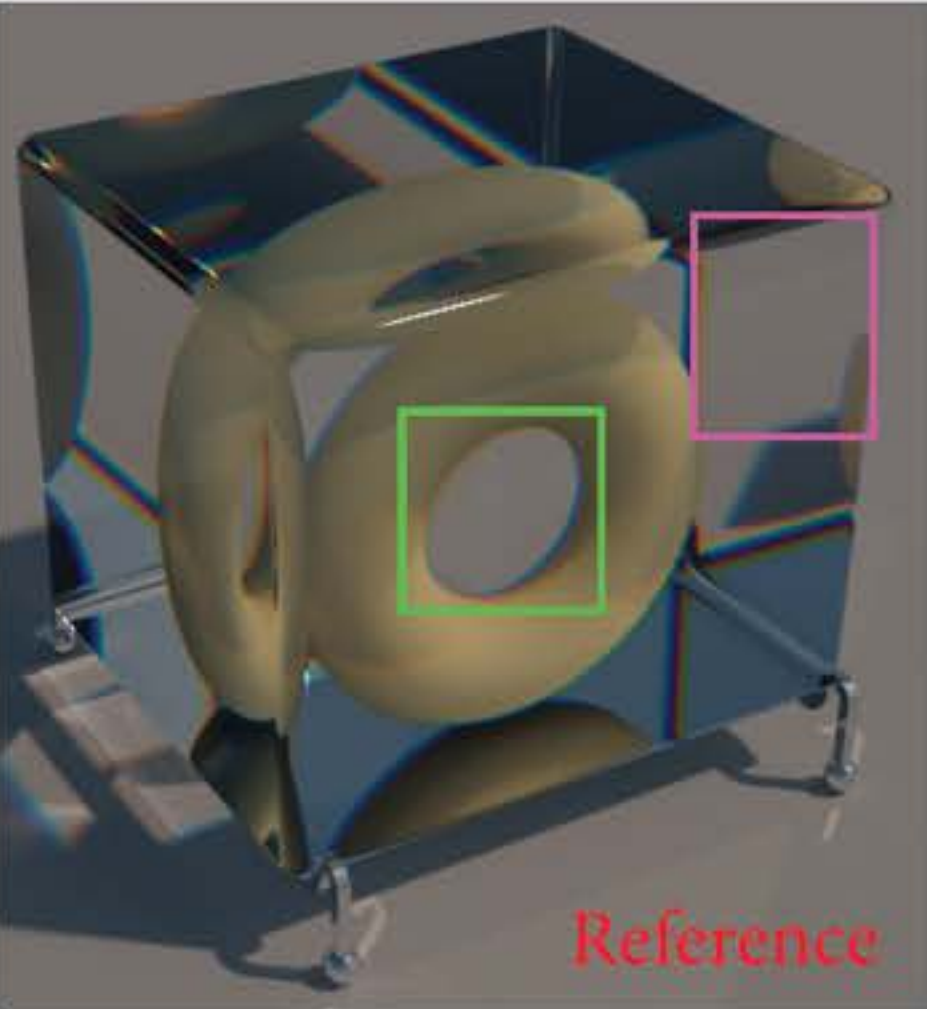


# Results



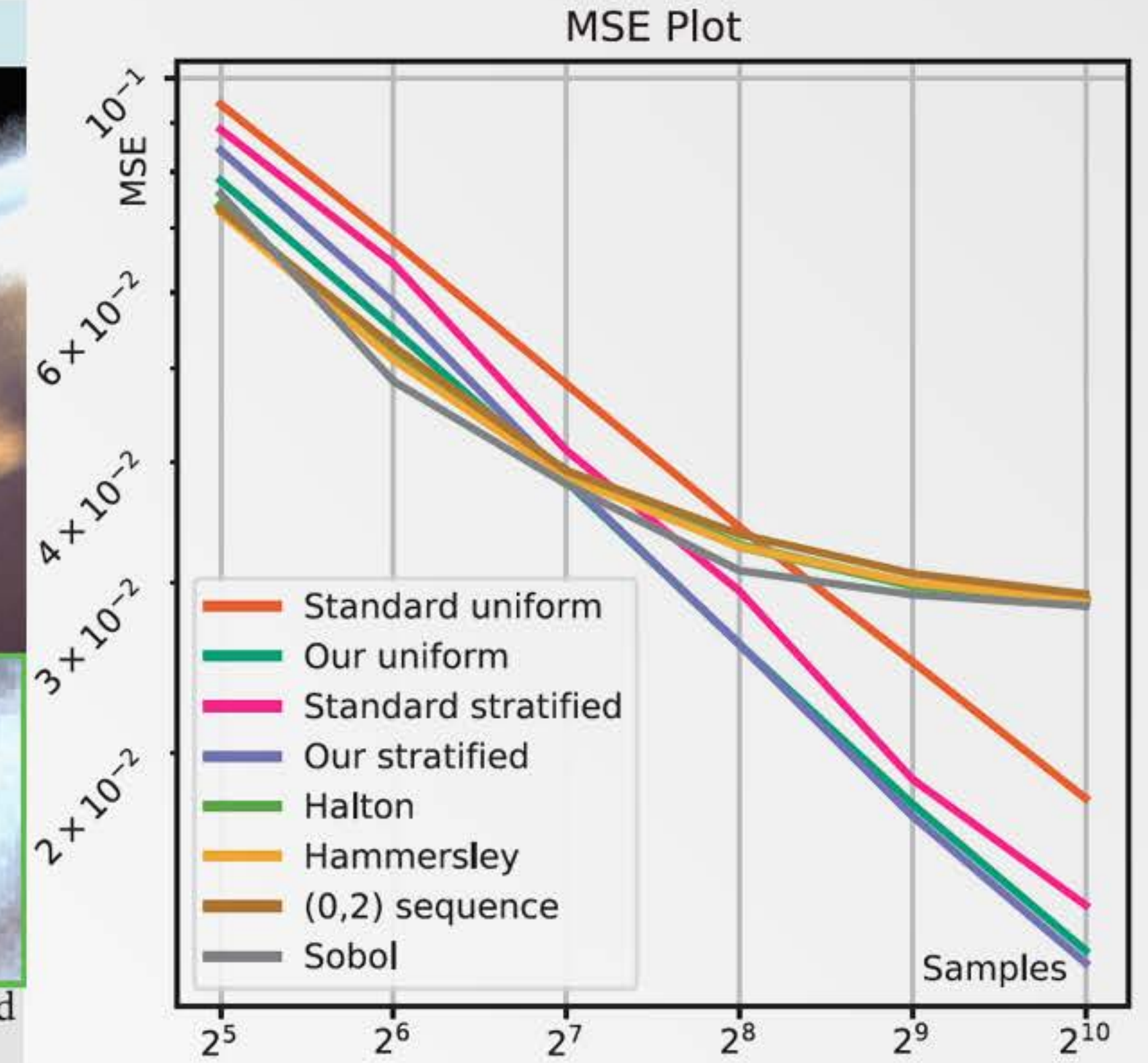
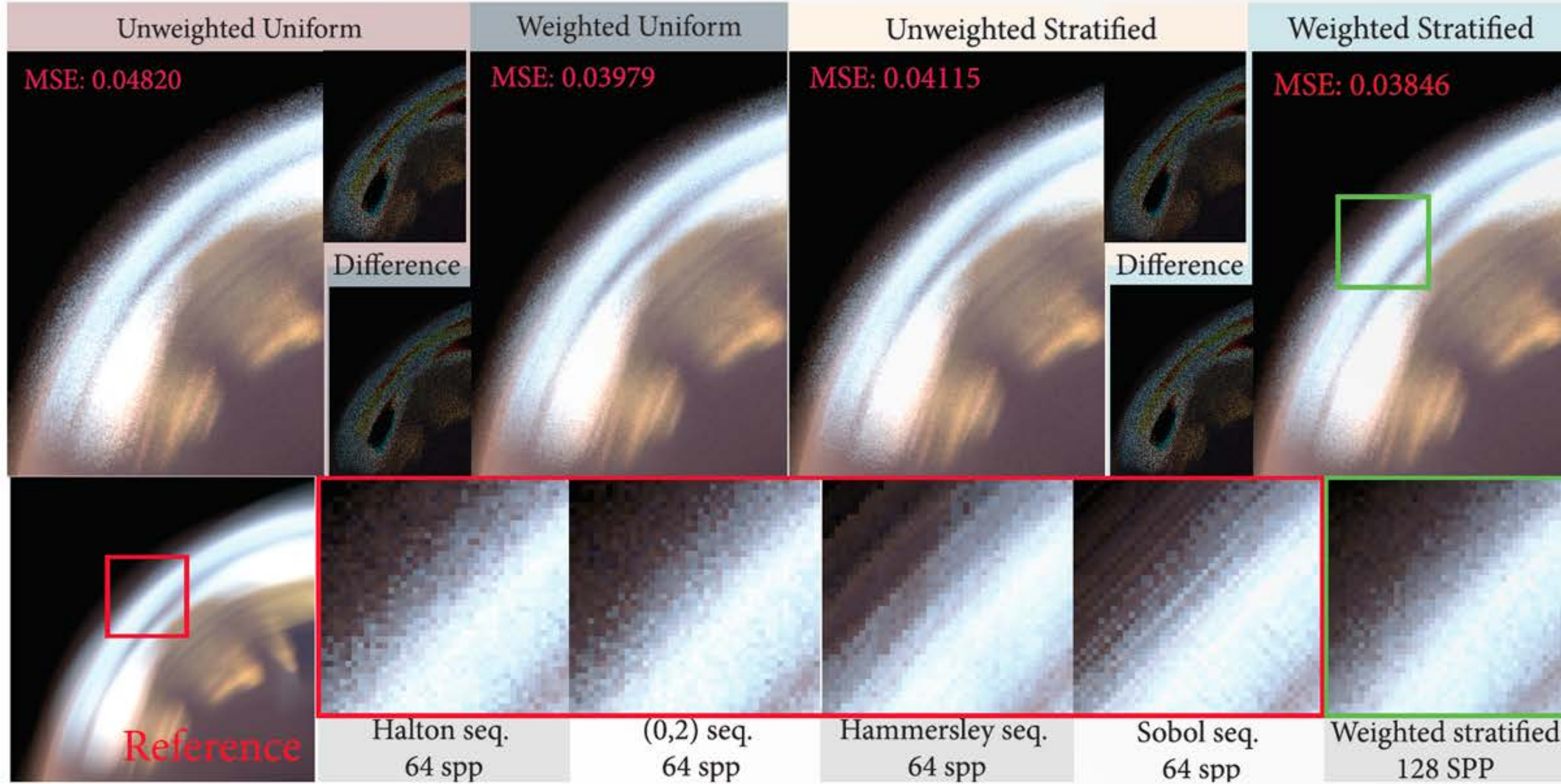


# Results



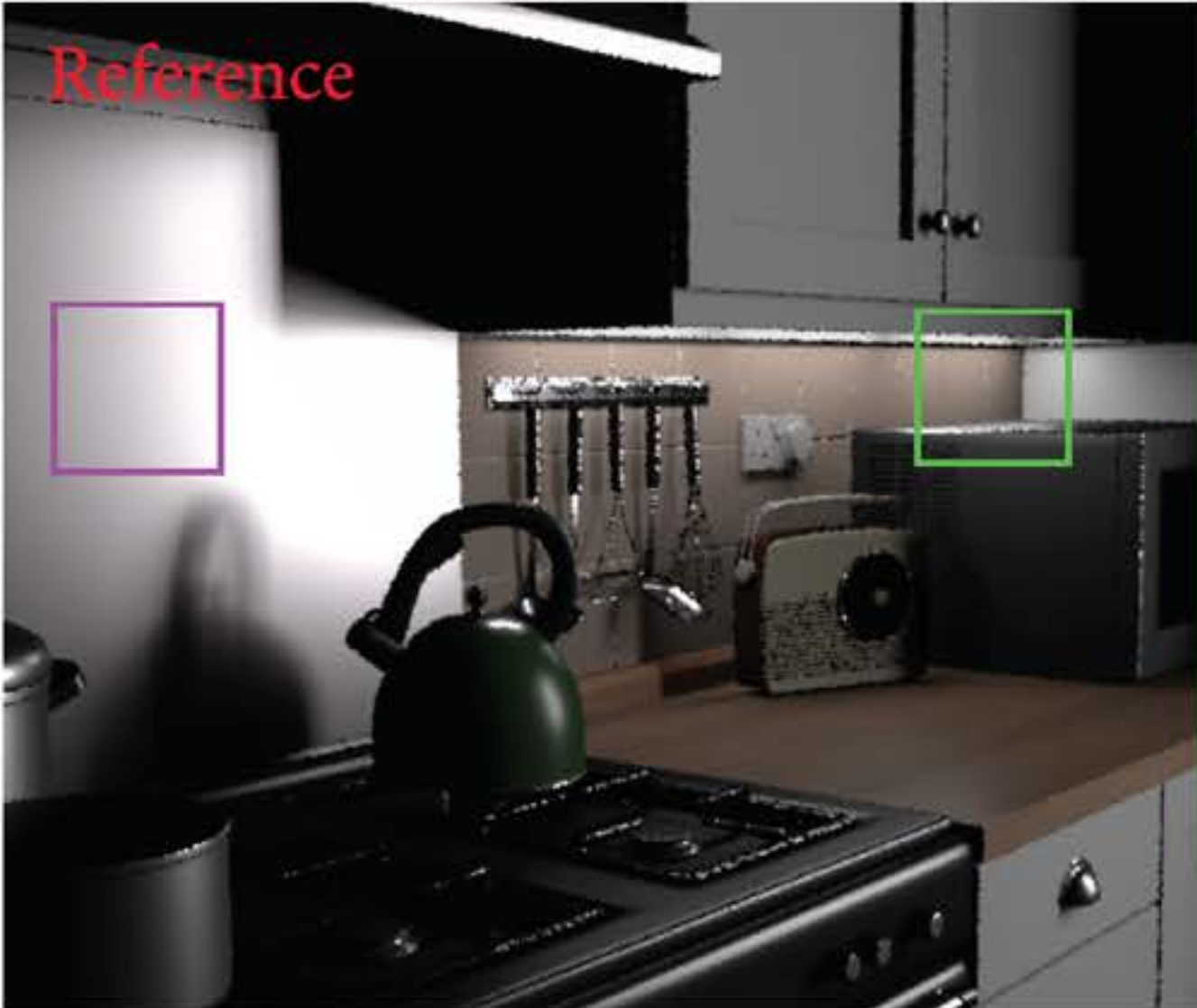


# Results

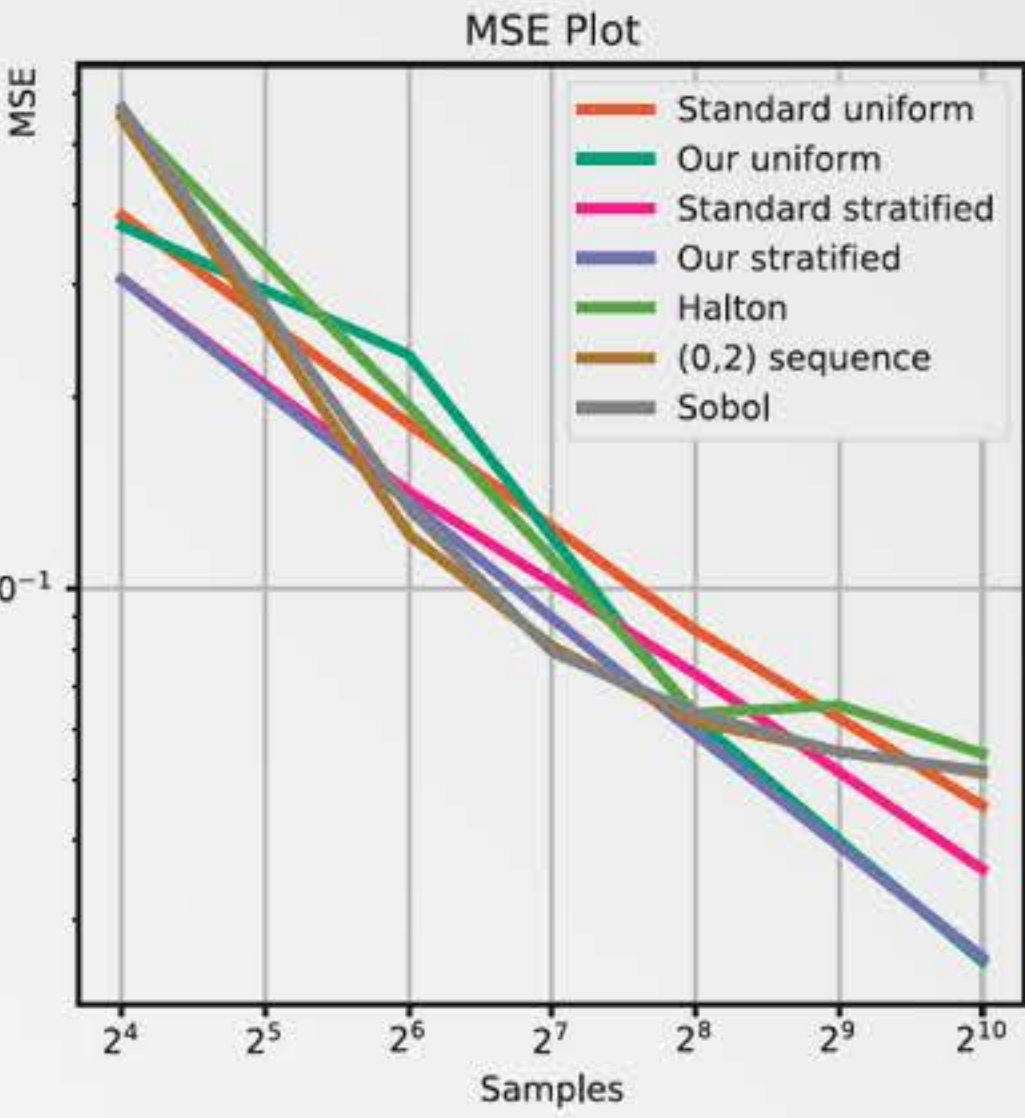




# Results



Weighted Uniform 64 SPP	Uniform 256 SPP	Weighted Uniform 256 SPP	Weighted Uniform 128 SPP	Uniform 256 SPP	Weighted Uniform 256 SPP
(a)	(b)	(c)	(d)	(e)	(f)
(g)	(h)	(i)	(j)	(k)	(l)
Sobol seq. 64 SPP	Halton seq. 64 SPP	Weighted Stratified 64 SPP	Sobol seq. 64 SPP	(0,2) seq. 64 SPP	Weighted Stratified 64 SPP





# Results



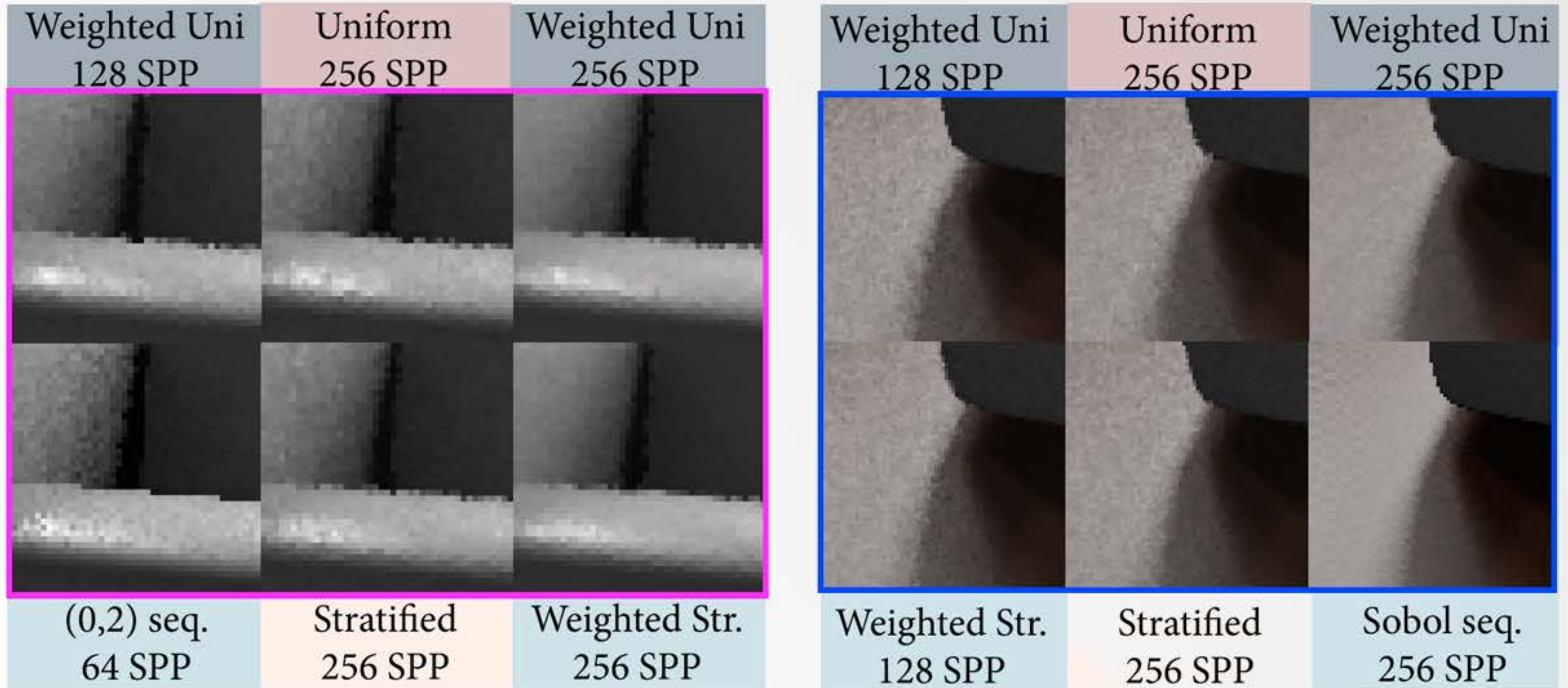
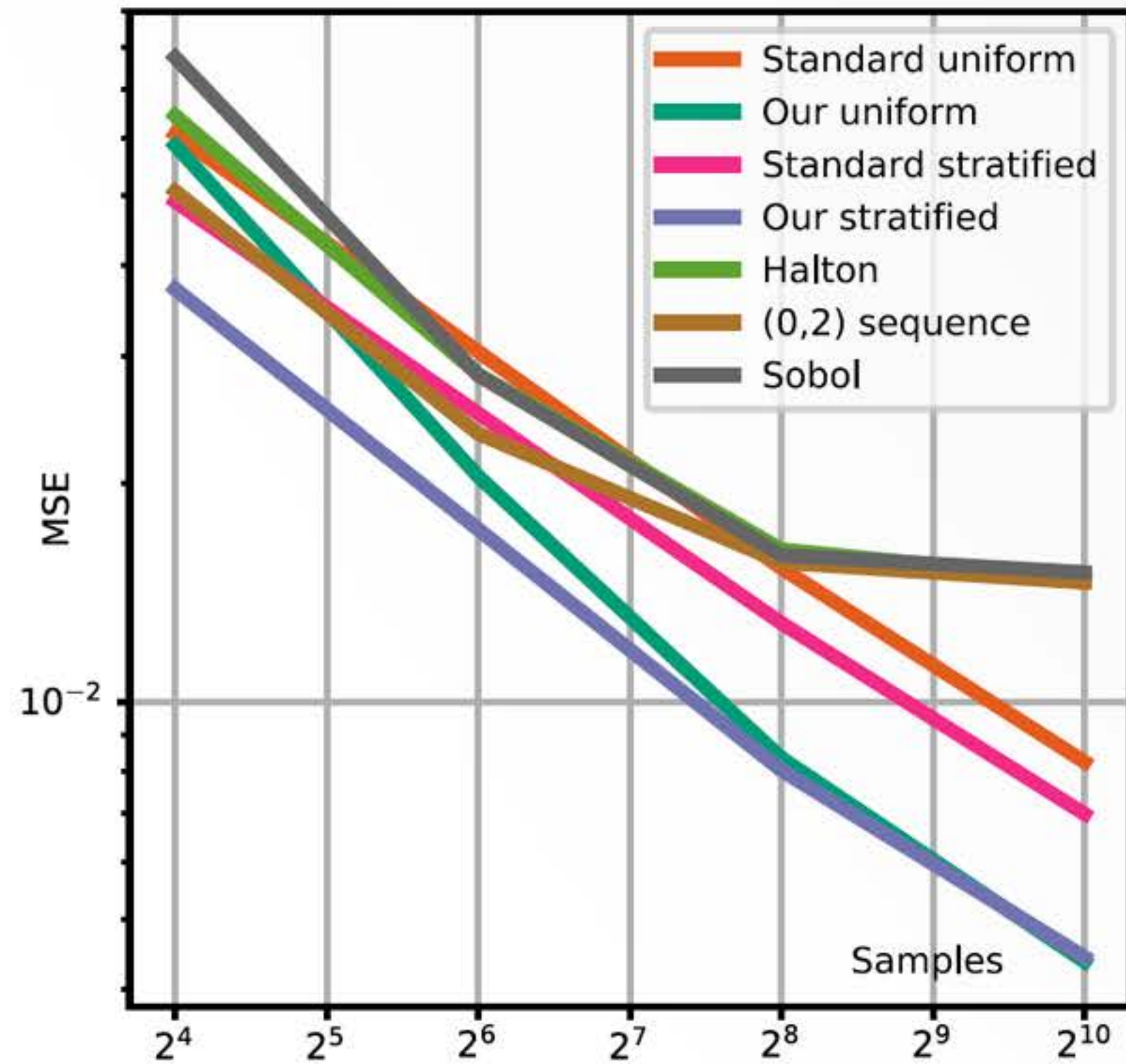
Weighted uni 64 SPP	Uniform 256 SPP	Weighted Uni 256 SPP	Weighted Uni 128 SPP	Uniform 256 SPP	Weighted Uni 256 SPP
Sobol seq. 64 SPP	Stratified 256 SPP	Weighted Str. 256 SPP	Weighted Str. 128 SPP	Halton seq. 256 SPP	Weighted Str. 256 SPP





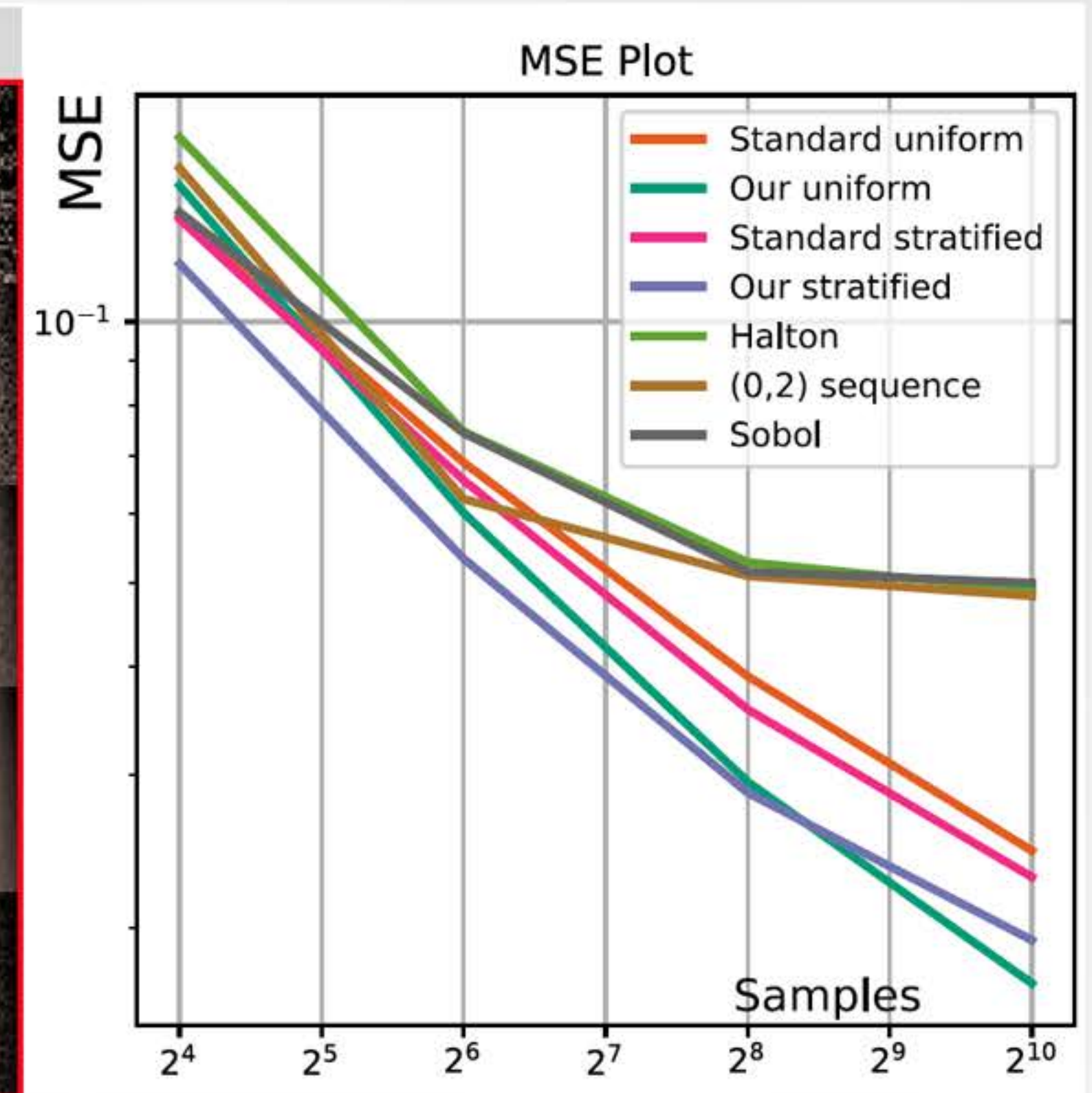
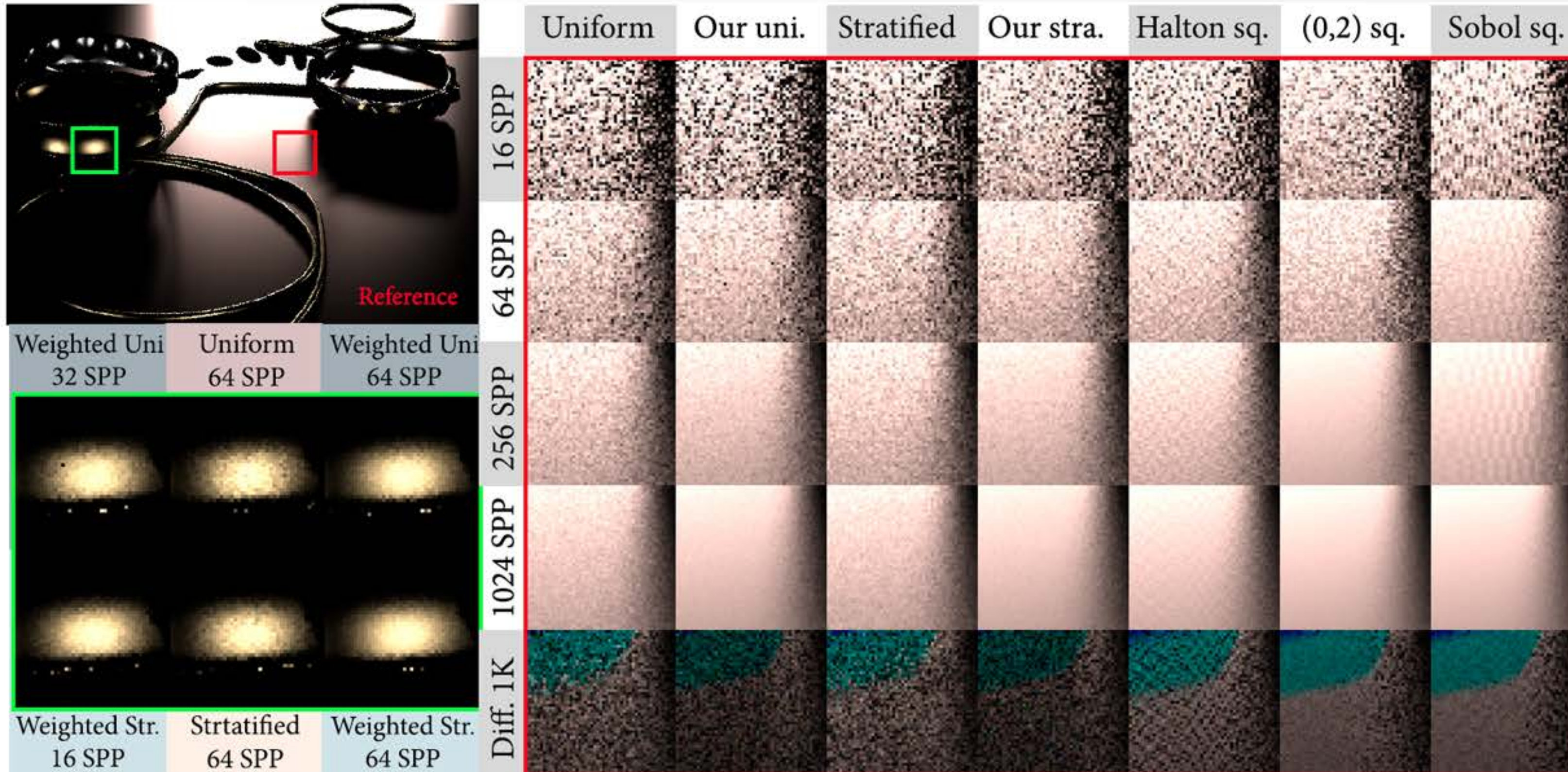
# Results

MSE Plot





# Results





# Implementation Details

## Precomputing samples and weights

Small runtime overhead

Reusing across render tiles



# Limitations

Limited in dimensionality

Voronoi tessellation expensive  $>3D$

Only unbiased with 1D uniform samples



# Future Work

Extend unbiased solution to higher dimension

Extend unbiased solution to non-uniform samples





# Conclusion

Simple reweighting scheme for Monte Carlo integration

Unbiased 1D solution for uniform samples and piece-wise non-uniform

Effective and efficient

Robust comparing against Quasi Monte Carlo



Thank you!

